

CSE 250

Data Structures

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Day 24
Heaps, Sets, Bags, and Ordered Trees

Textbook Ch. 16, 18

Announcements

Priority Queues

Lazy - Fast Enqueue, Slow Dequeue

Proactive - Slow Enqueue, Fast Dequeue

??? - Fast(-ish) Enqueue, Fast(-ish) Dequeue

Binary Heaps

Organize our priority queue as a directed tree

Directed: A directed edge from a to b means that $a \geq b$

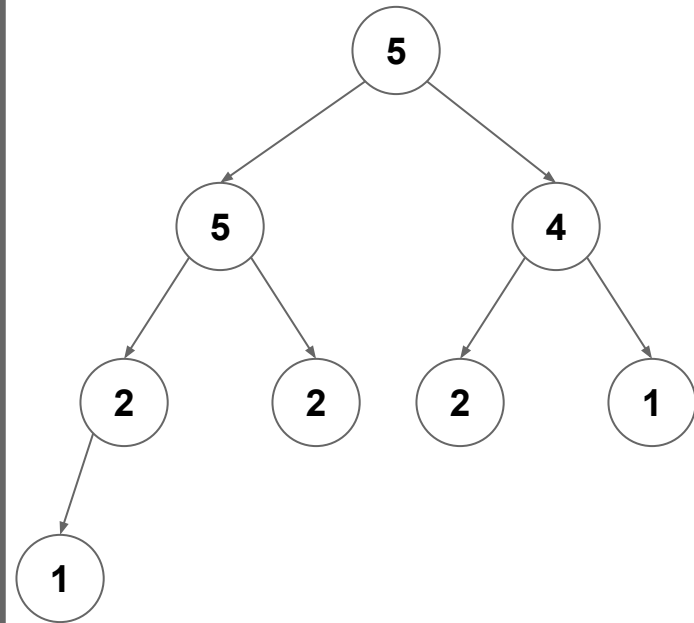
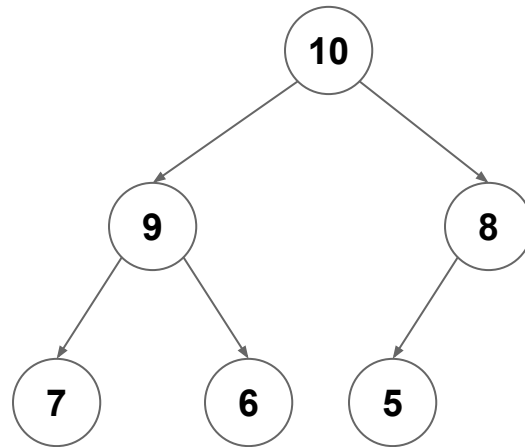
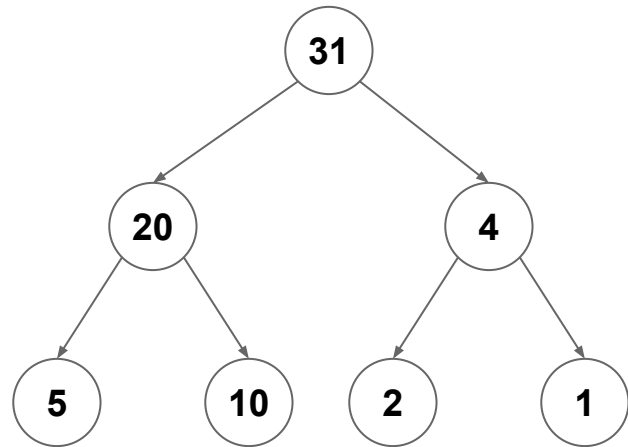
Binary: Max out-degree of 2 (easy to reason about)

Complete: Every "level" except the last is full (from left to right)

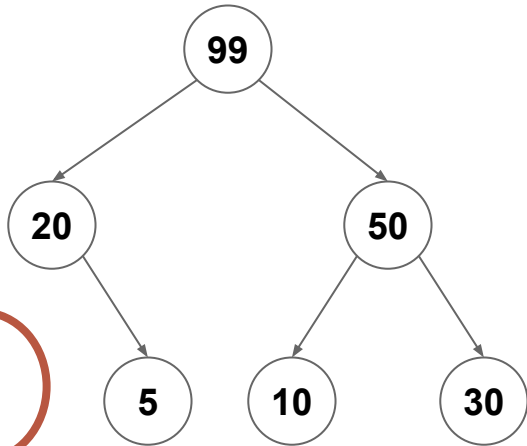
Balanced: TBD (basically, all leaves are roughly at the same level)

This makes it easy to encode into an array

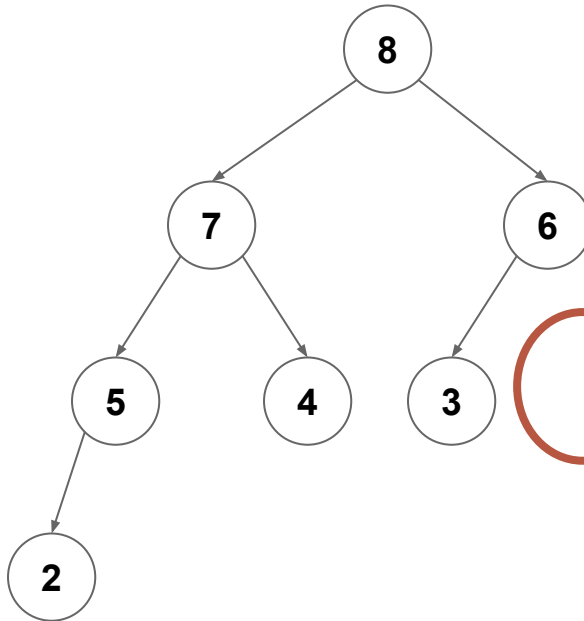
Valid Max Heaps



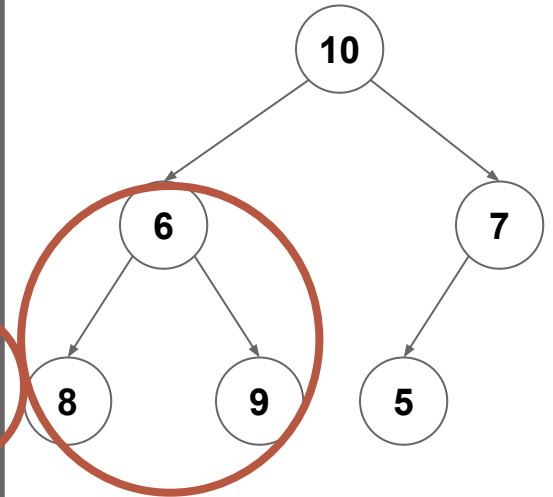
Invalid Max Heaps



Need to fill from left to right



Need complete levels



Children must be less than or equal to parents

Heaps

What is the depth of a binary heap containing n items?

$$n = O \left(\sum_{i=1}^{\ell_{max}} 2^i \right) = O(2^{\ell_{max}})$$

$$\ell_{max} = O(\log(n))$$

The Heap ADT

enqueue (elem: A) : Unit *[AKA pushHeap]*
Place an item into the heap

dequeue : A *[AKA popHeap]*
Remove and return the maximal element from the heap

head : A
Peek at the maximal element in the heap

length : Int
The number of elements in the heap

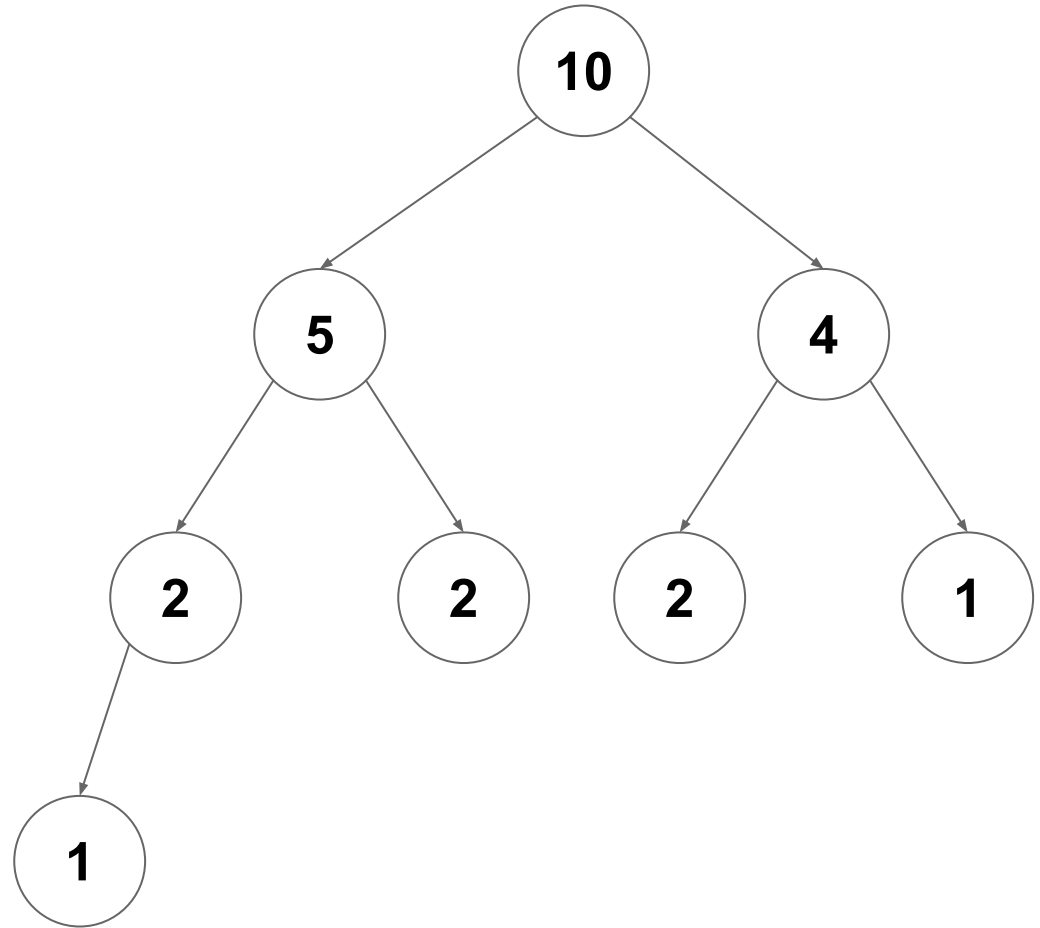
Heap.enqueue

Idea: Insert the element at the next available spot, then fix the heap.

1. Call the insertion point **current**
2. While **current** \neq **root** and **current** $>$ **parent**
 - a. Swap **current** with **parent**
 - b. Repeat with **current** \leftarrow **parent**

Heap . enqueue

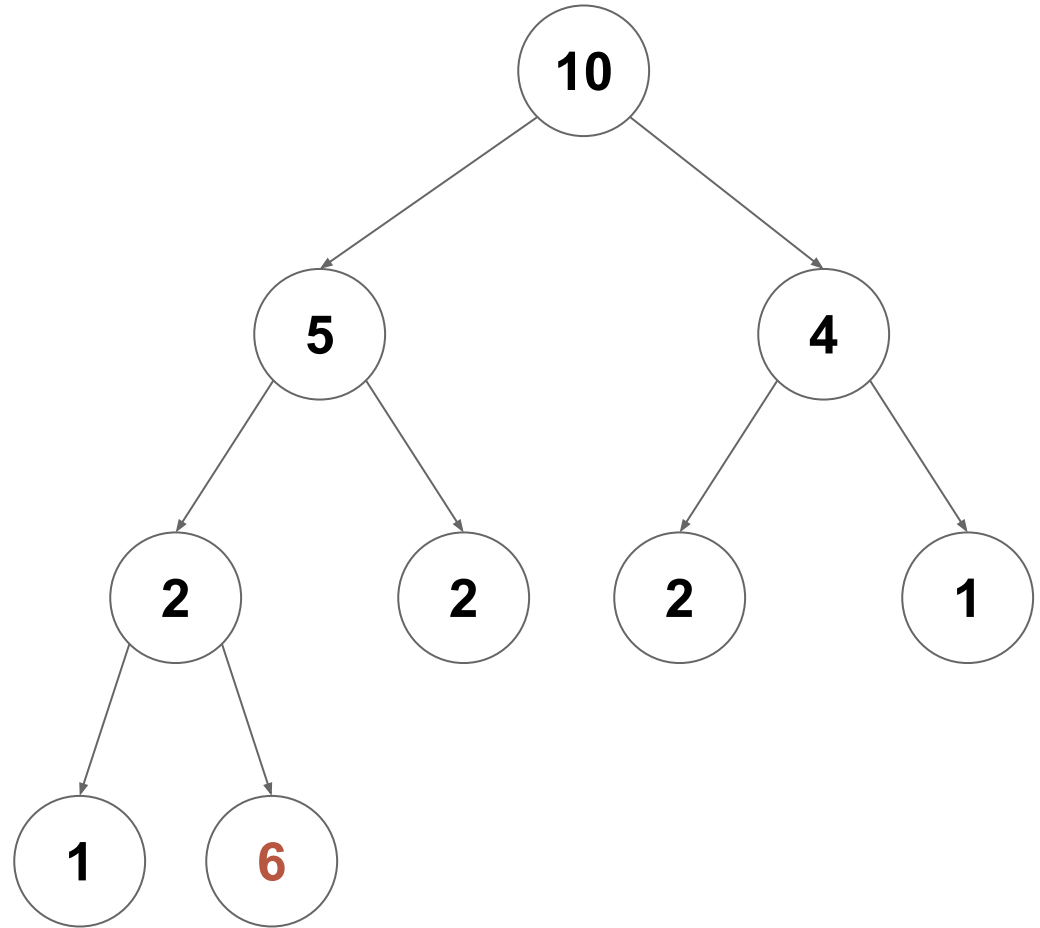
What if we enqueue 6?



Heap . enqueue

What if we enqueue 6?

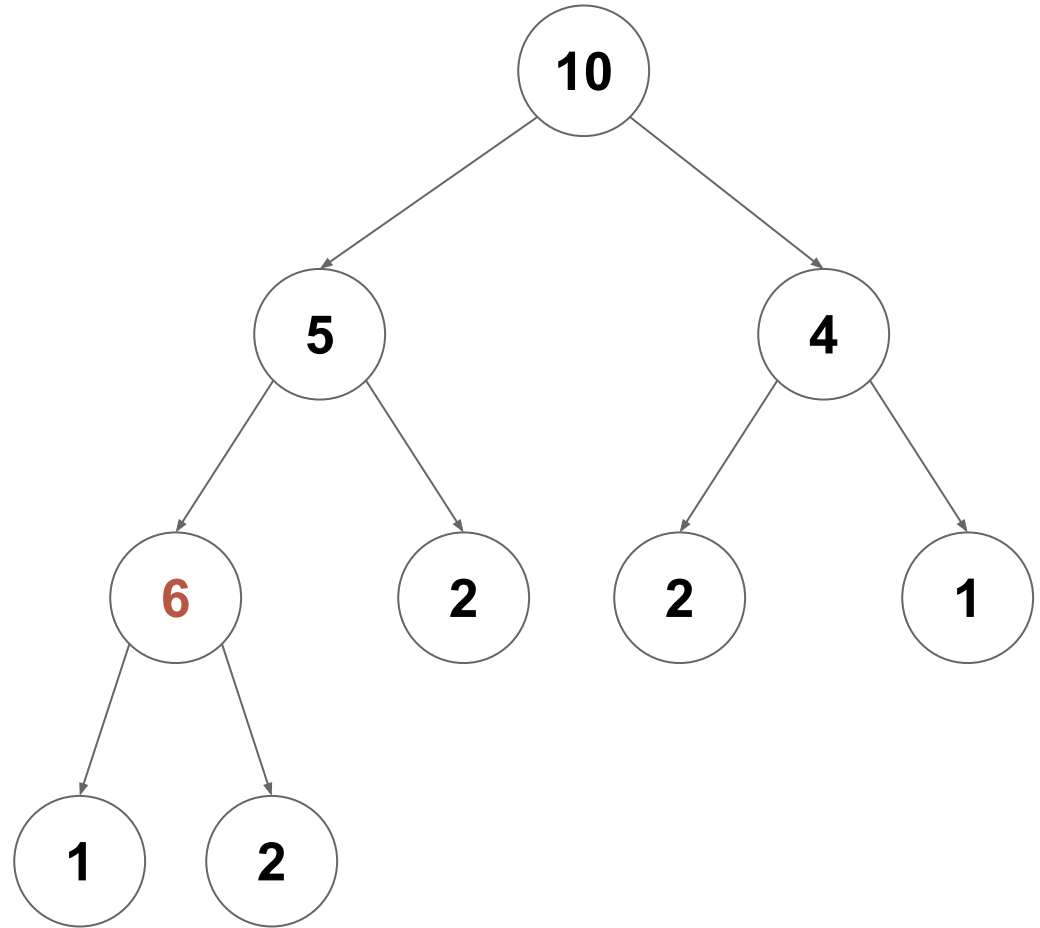
Place in the next available spot



Heap . enqueue

What if we enqueue 6?

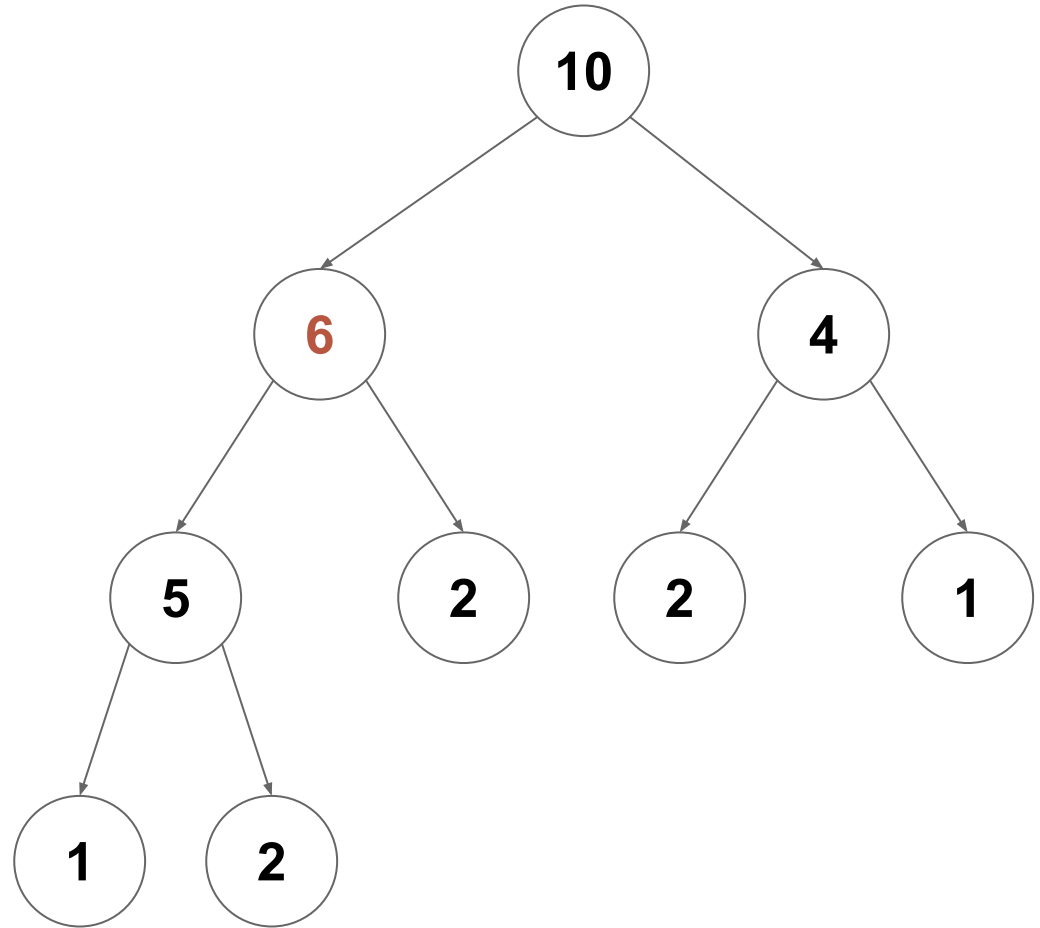
Swap with parent if it is bigger than the parent



Heap . enqueue

What if we enqueue 6?

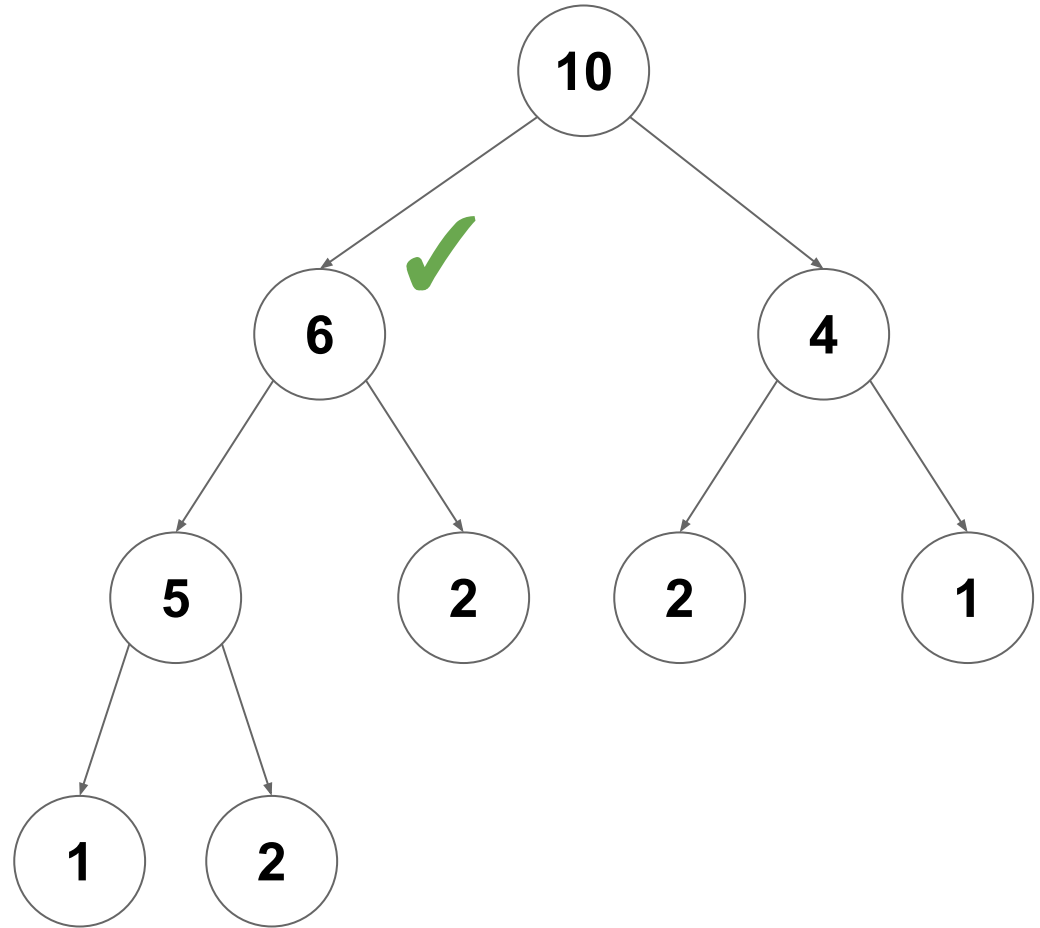
Continue swapping
upwards...



Heap . enqueue

What if we enqueue 6?

Stop swapping when we are no longer bigger than our parent



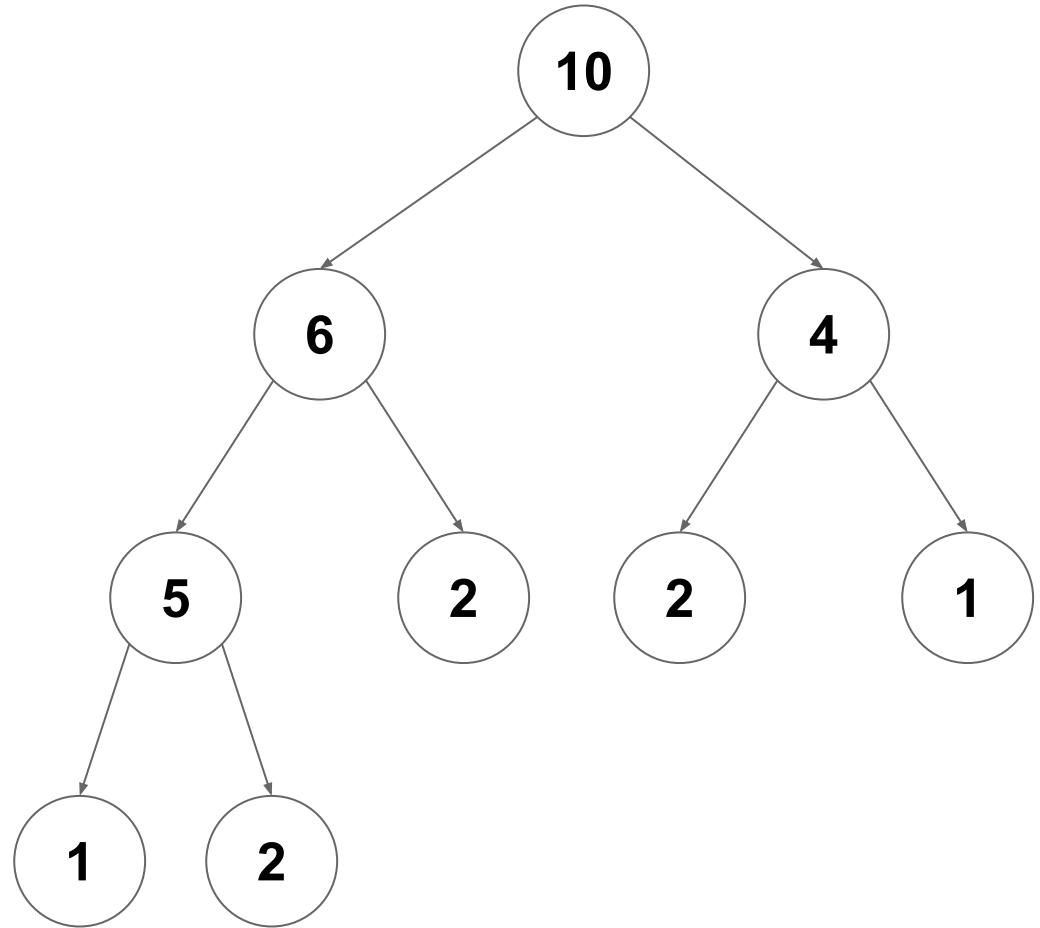
Heap . dequeue

Idea: Replace root with the last element then fix the heap

1. Start with `current ← root`
2. While `current` has a `child > current`
 - a. Swap `current` with its largest `child`
 - b. Repeat with `current ← child`

Heap . dequeue

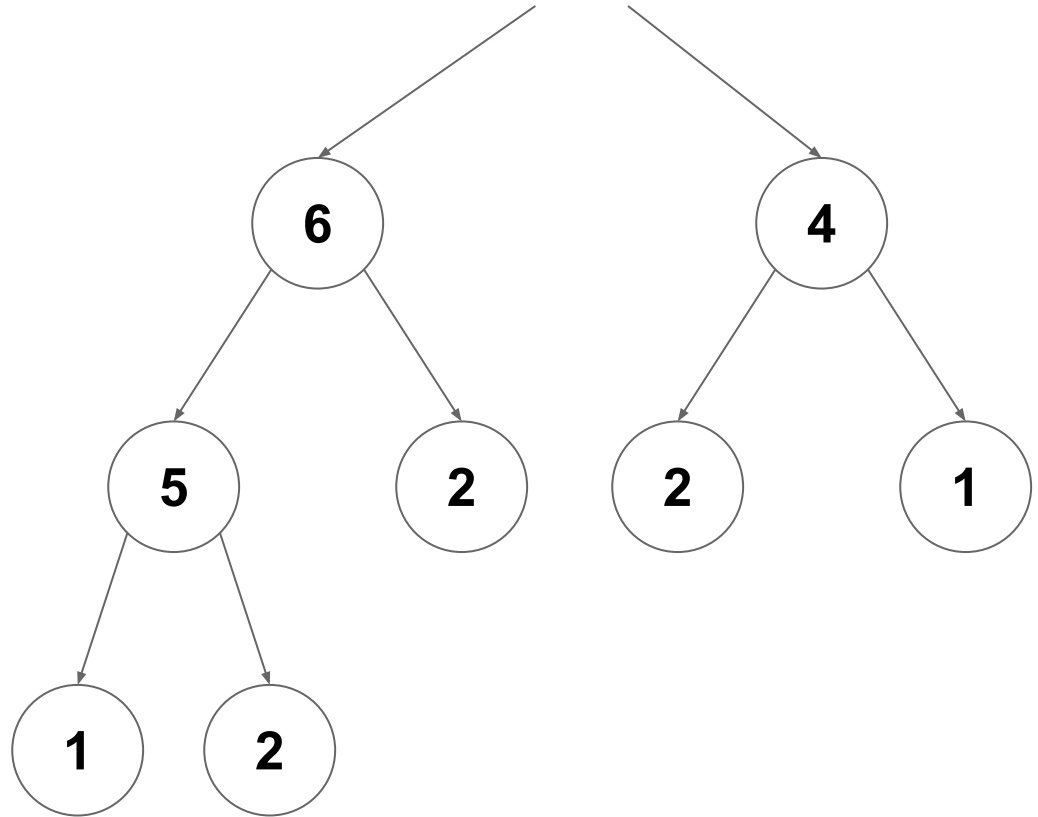
What if we call dequeue?



Heap . dequeue

What if we call dequeue?

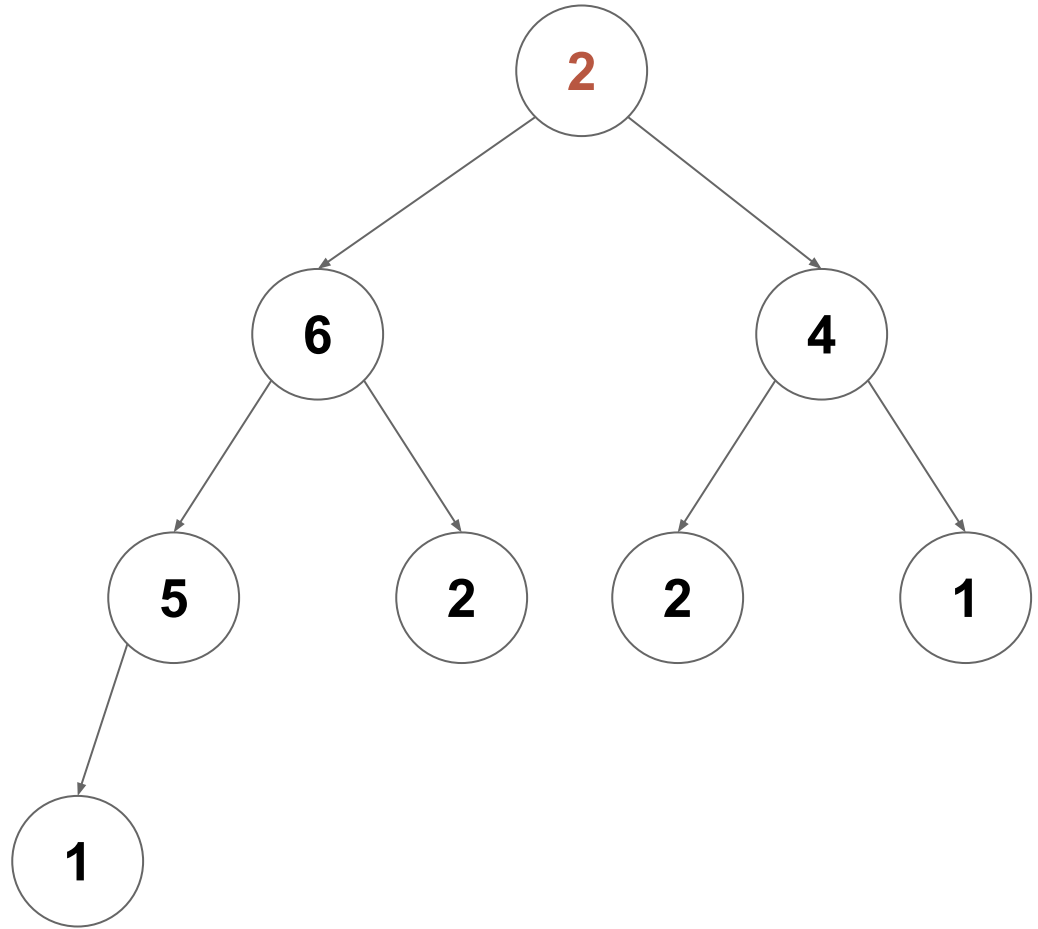
Remove and return the
root



Heap.dequeue

What if we call dequeue?

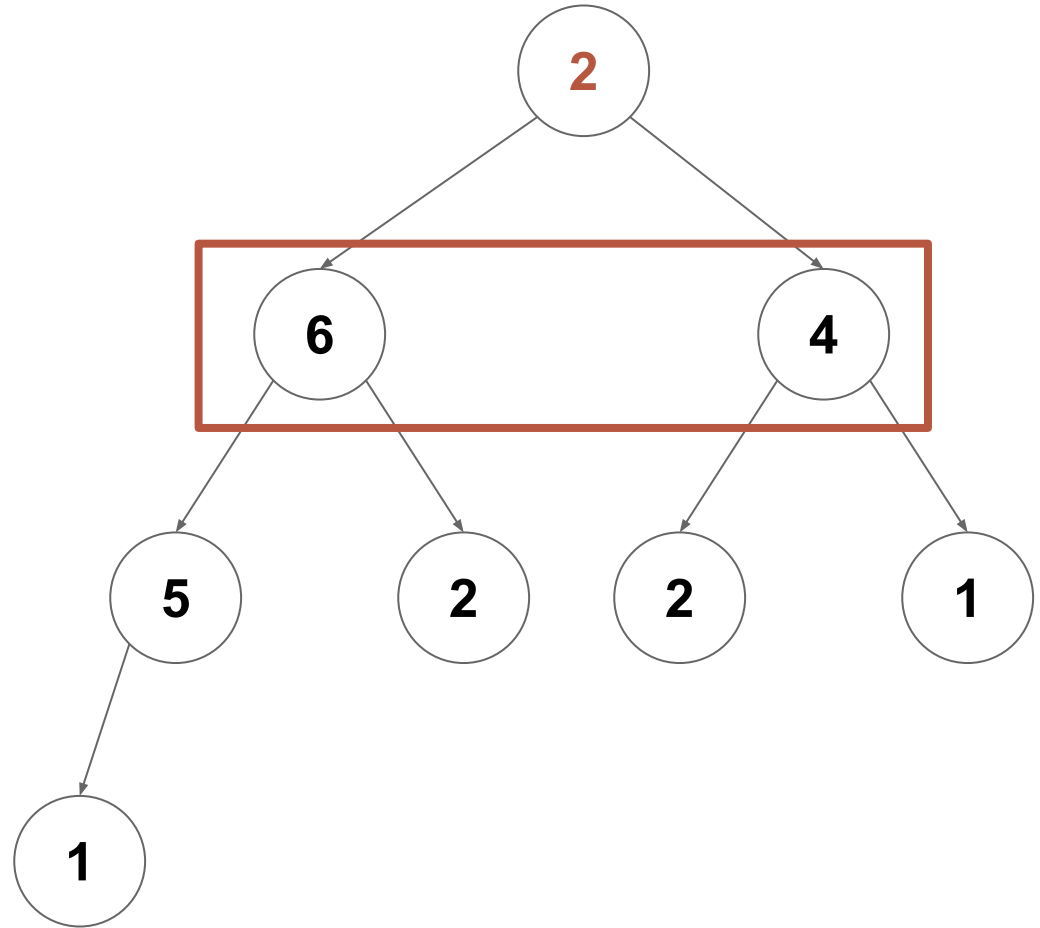
Make the last item the
new root



Heap . dequeue

What if we call dequeue?

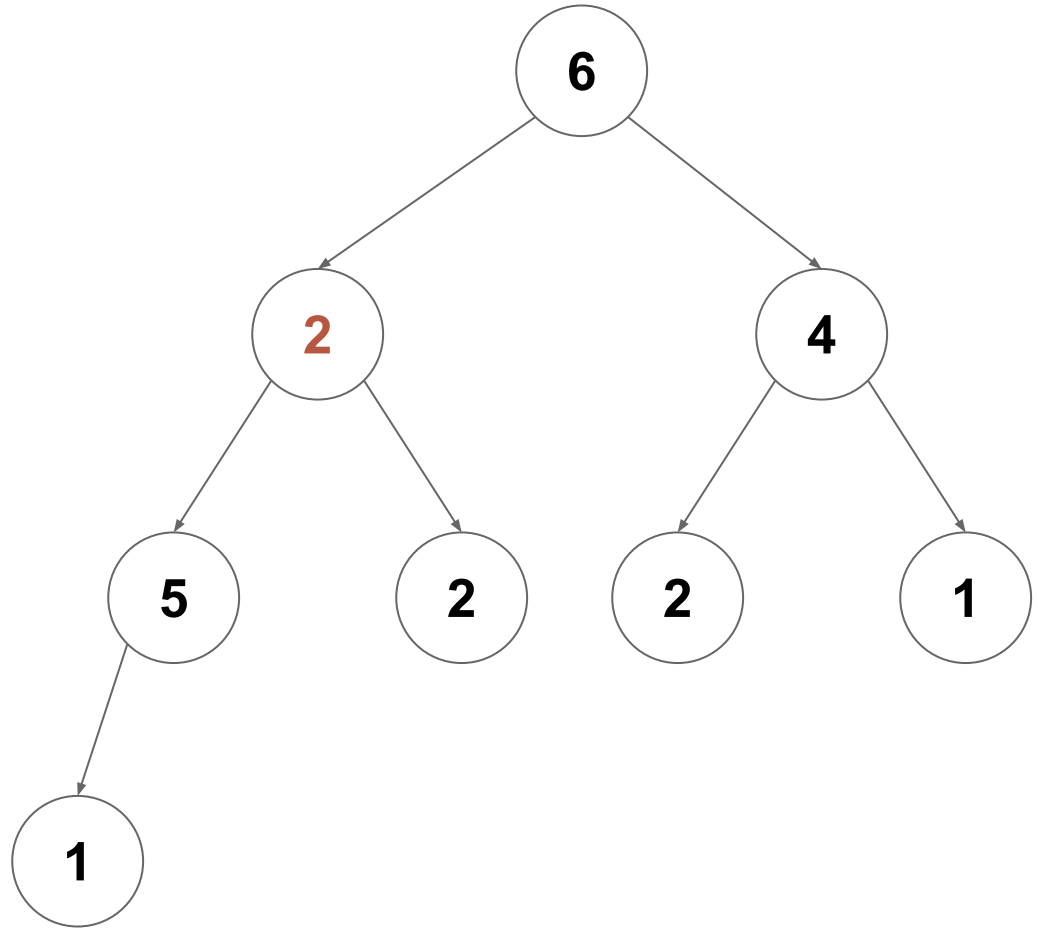
Check for our largest child



Heap . dequeue

What if we call dequeue?

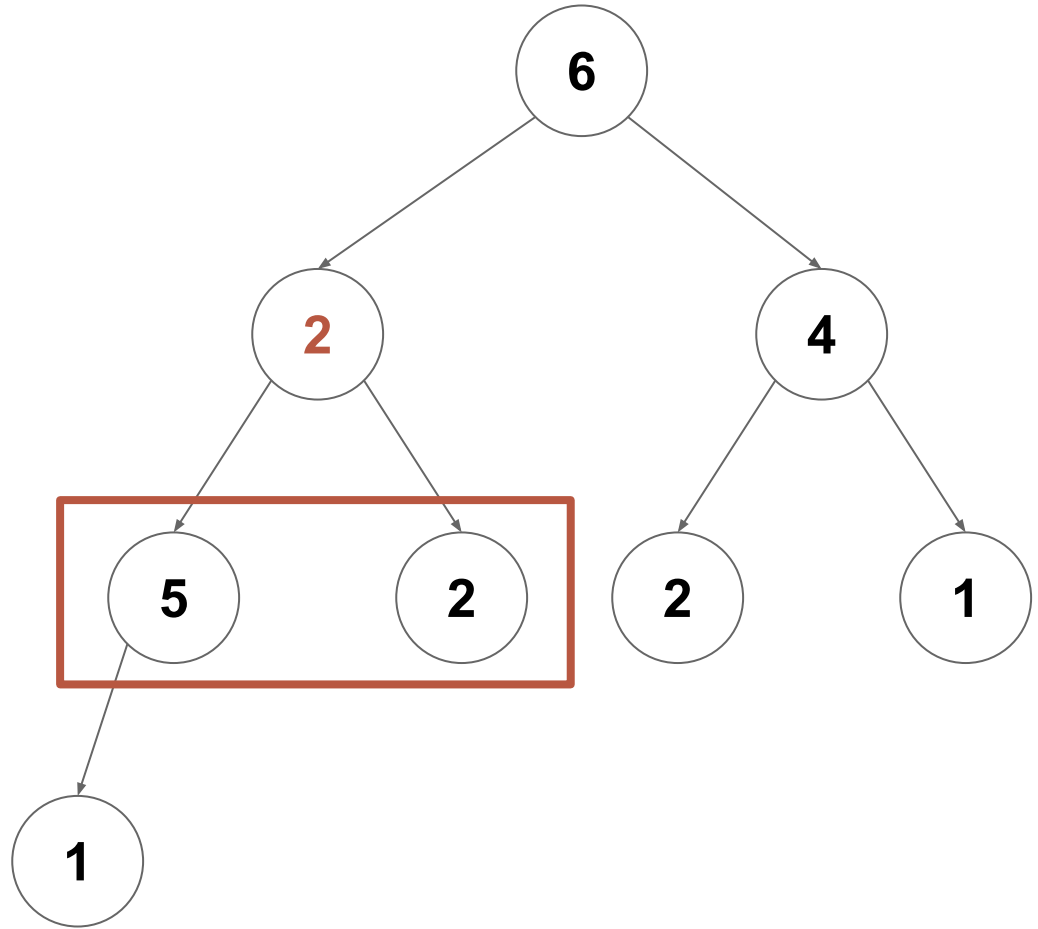
If the largest child is bigger than us, swap



Heap . dequeue

What if we call dequeue?

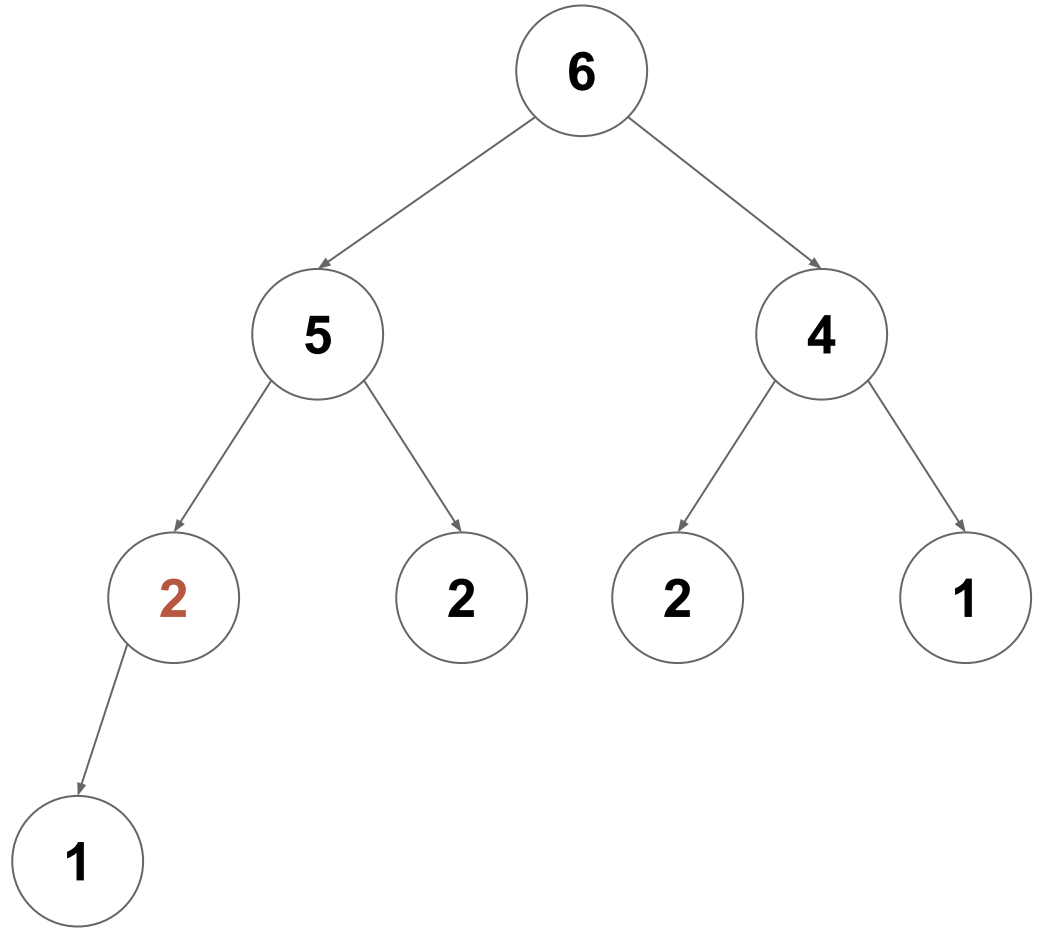
Continue swapping down the tree as necessary...



Heap . dequeue

What if we call dequeue?

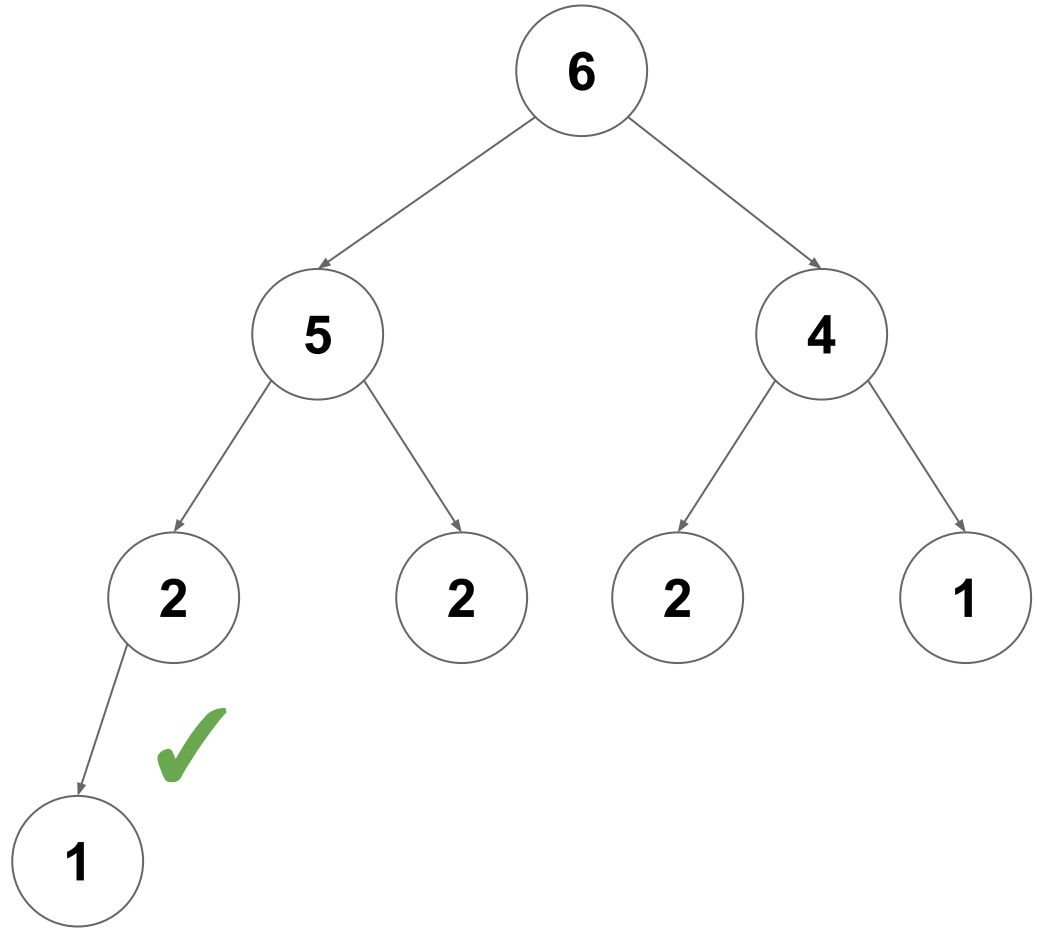
Continue swapping down the tree as necessary...



Heap . dequeue

What if we call dequeue?

Stop swapping when our children are no longer bigger



Storing heaps

Notice that:

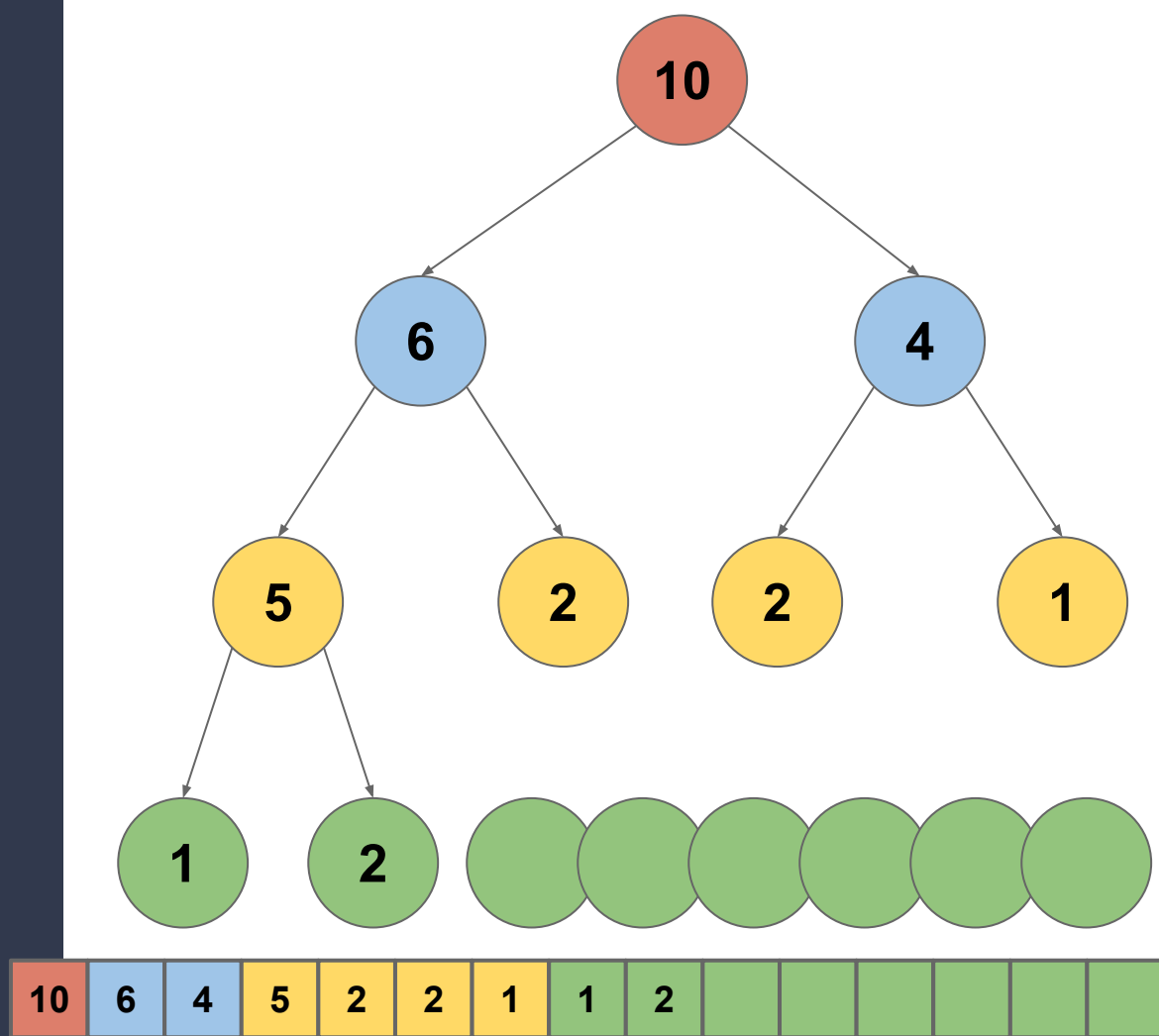
1. Each level has a maximum size
2. Each level grows left-to-right
3. Only the last layer grows

How can we compactly store a heap?

Idea: Use an **ArrayBuffer**

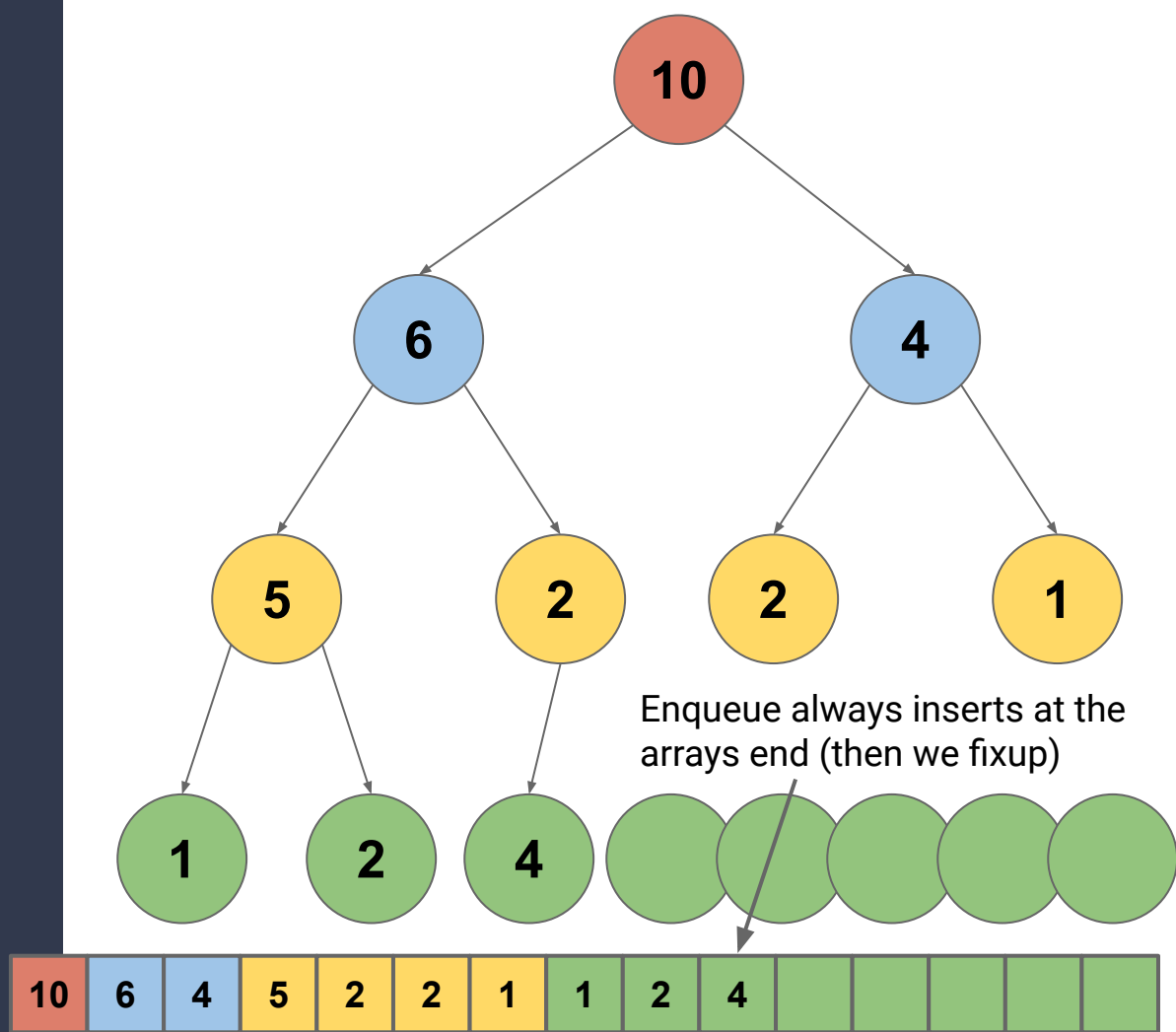
Storing Heaps

How can we store this heap in an array buffer?



Storing Heaps

How can we store this heap in an array buffer?



Runtime Analysis

enqueue

- **Append to ArrayBuffer:** amortized $O(1)$ (*worst-case $O(n)$*)
- **fixUp:** $O(\log(n))$ fixes, each one costs $O(1) = O(\log(n))$
- **Total:** amortized $O(\log(n))$ (*worst-case $O(n)$*)

dequeue

- **Remove end of ArrayBuffer:** $O(1)$
- **fixDown:** $O(\log(n))$ fixes, each one costs $O(1) = O(\log(n))$
- **Total:** worst-case $O(\log(n))$

Priority Queues

Operation	Lazy	Proactive	Heap
enqueue	$O(1)$	$O(n)$	$O(\log(n))$
dequeue	$O(n)$	$O(1)$	$O(\log(n))$
head	$O(n)$	$O(1)$	$O(1)$

Heap Sort

1. Insert items into heap
2. Reconstruct sequence (in reverse order) with dequeue

7, 4, 8, 2, 5, 3, 9



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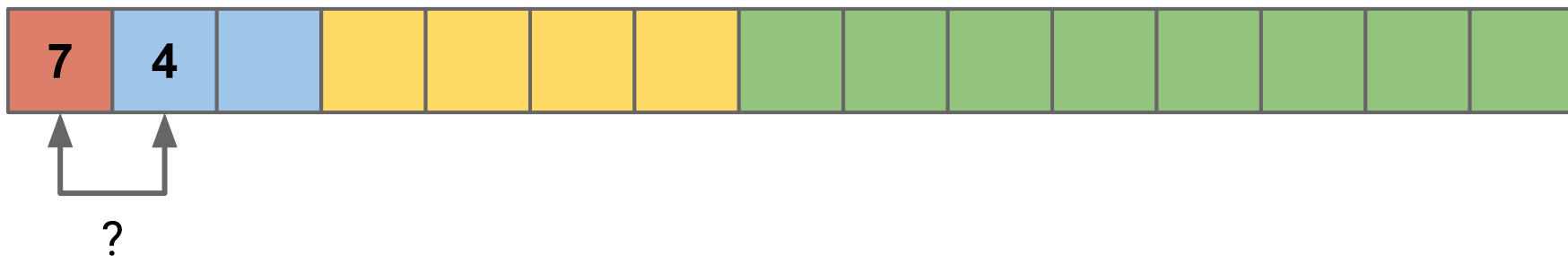
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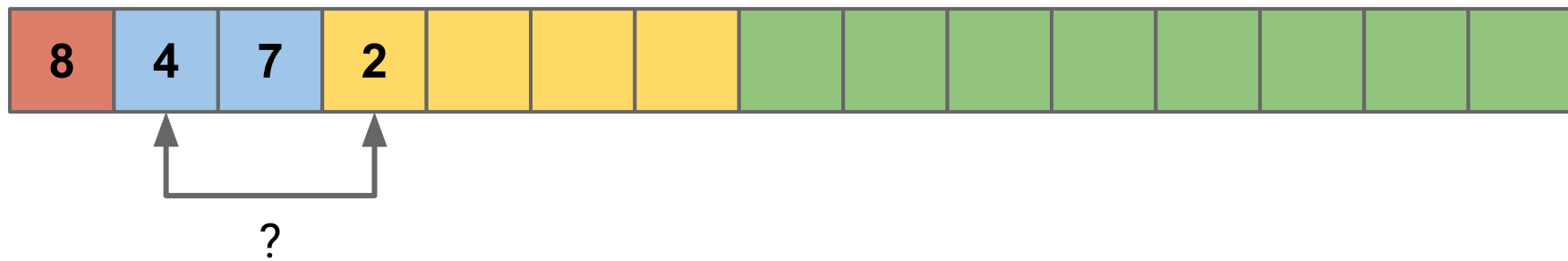
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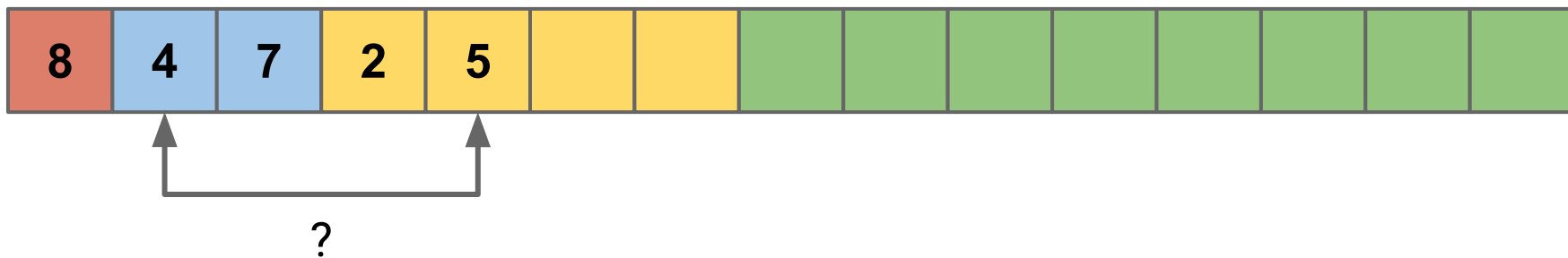
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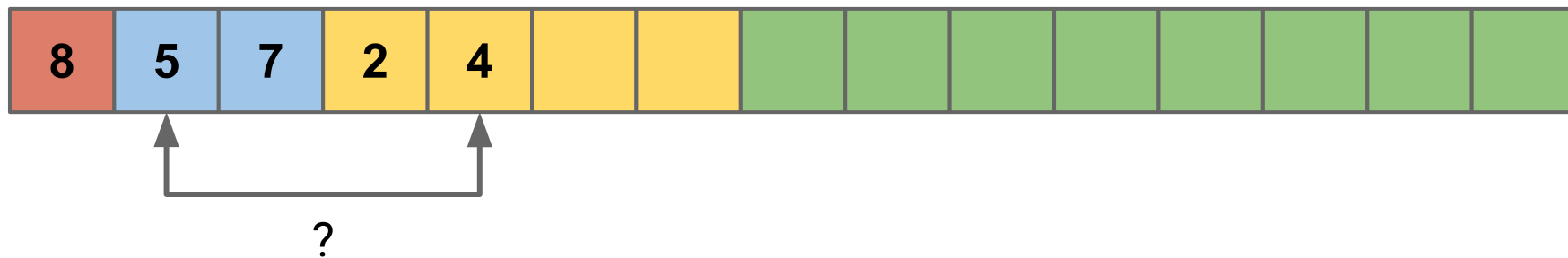
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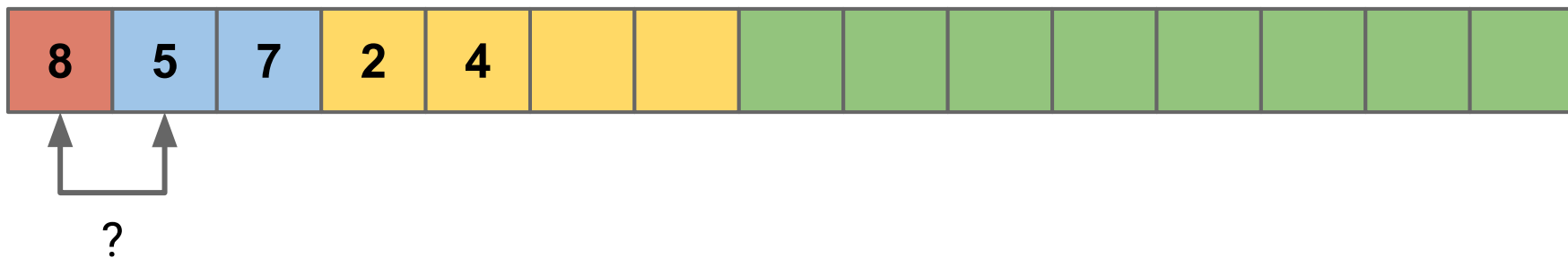
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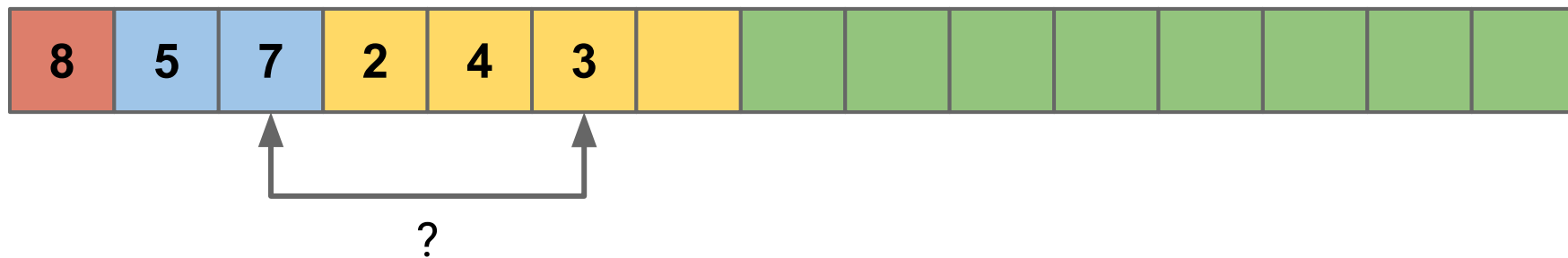
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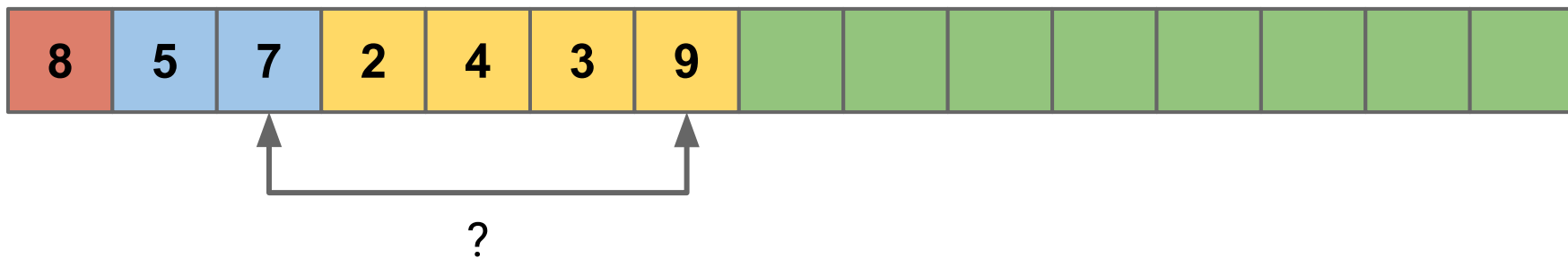
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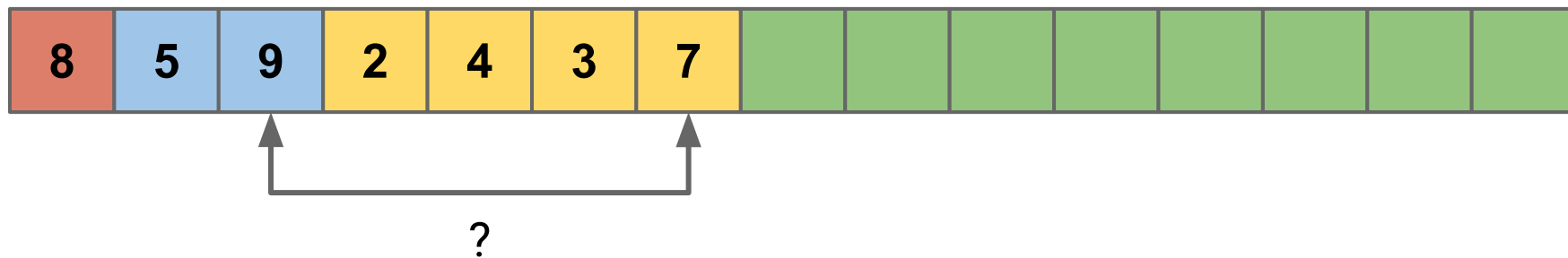
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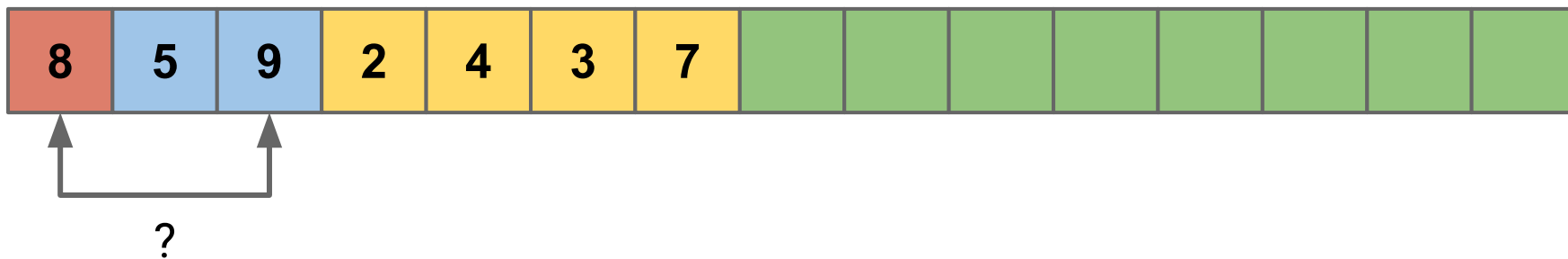
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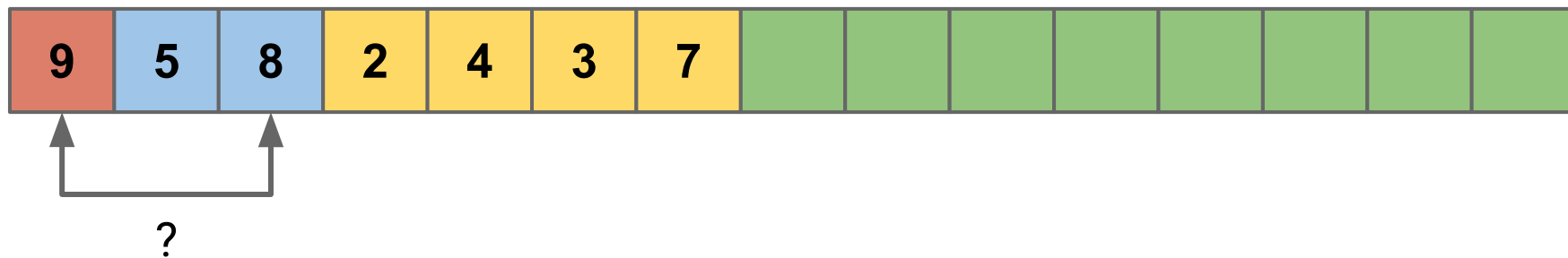
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8, 9

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?

8, 9

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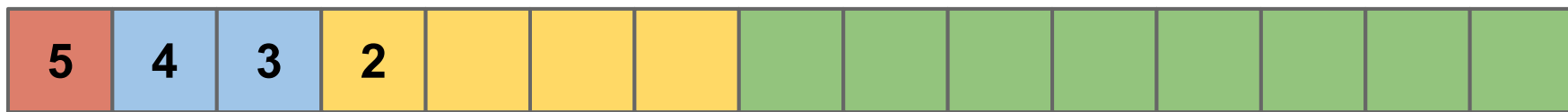
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2, 3, 4, 5, 7, 8, 9

Heap Sort

Heap Sort

Enqueue element i : $O(\log(i))$

Heap Sort

Enqueue element i : $O(\log(i))$

Dequeue element i : $O(\log(n - i))$

Heap Sort

Enqueue element i : $O(\log(i))$

Dequeue element i : $O(\log(n - i))$

$$\left(\sum_{i=1}^n O(\log(i)) \right) + \left(\sum_{i=1}^n O(\log(n - i)) \right)$$

Heap Sort

Enqueue element i : $O(\log(i))$

Dequeue element i : $O(\log(n - i))$

$$\left(\sum_{i=1}^n O(\log(i)) \right) + \left(\sum_{i=1}^n O(\log(n - i)) \right) < O(n \log(n))$$

Updating Heap Elements

What if we want to update a value in our Heap?

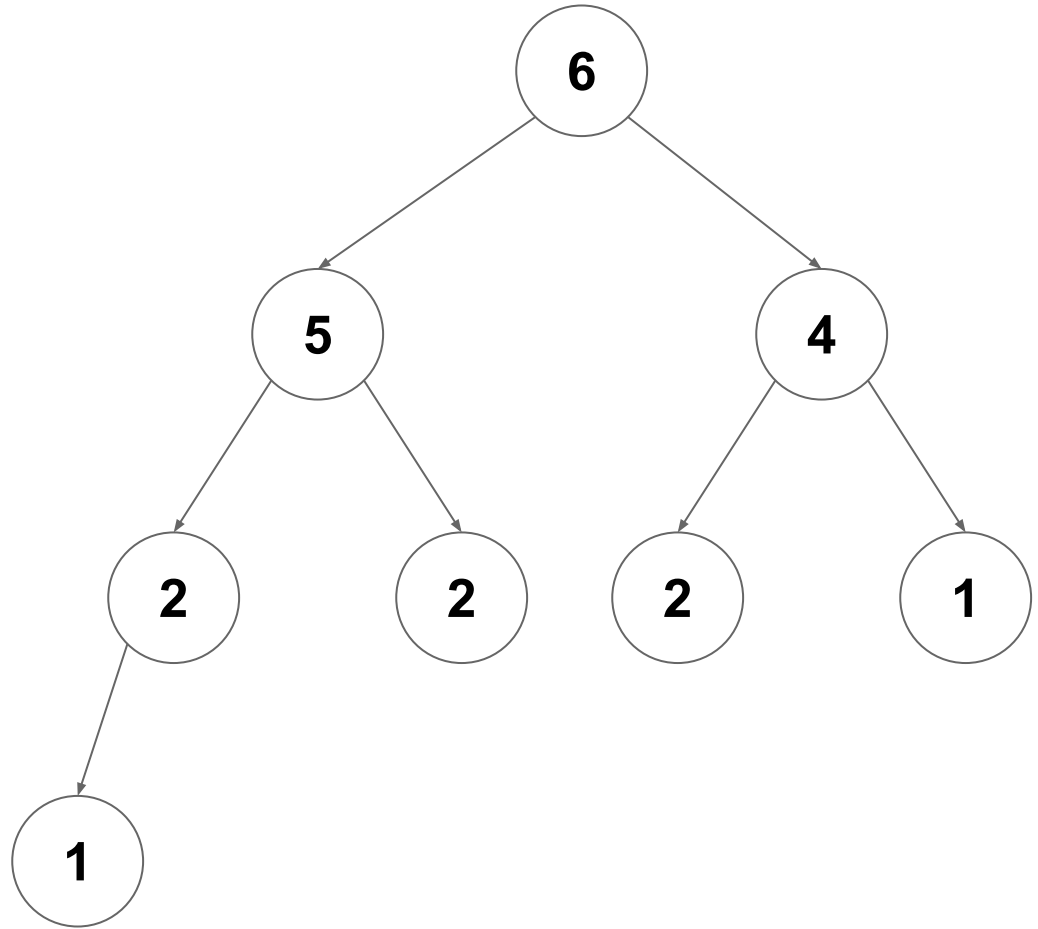
Updating Heap Elements

What if we want to update a value in our Heap?

After update we can just call `fixUp` or `fixDown` based on the new value

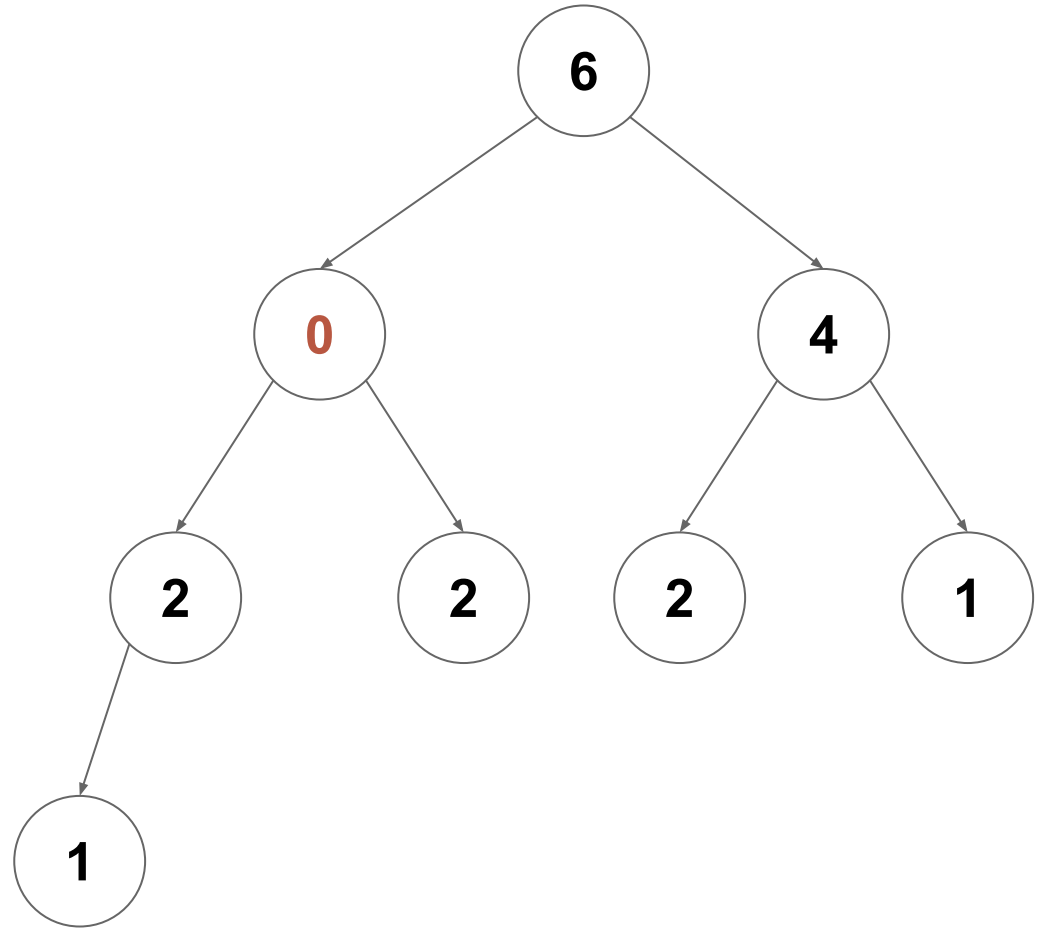
Heap . update

What if we change the value of the 5 node to 0?



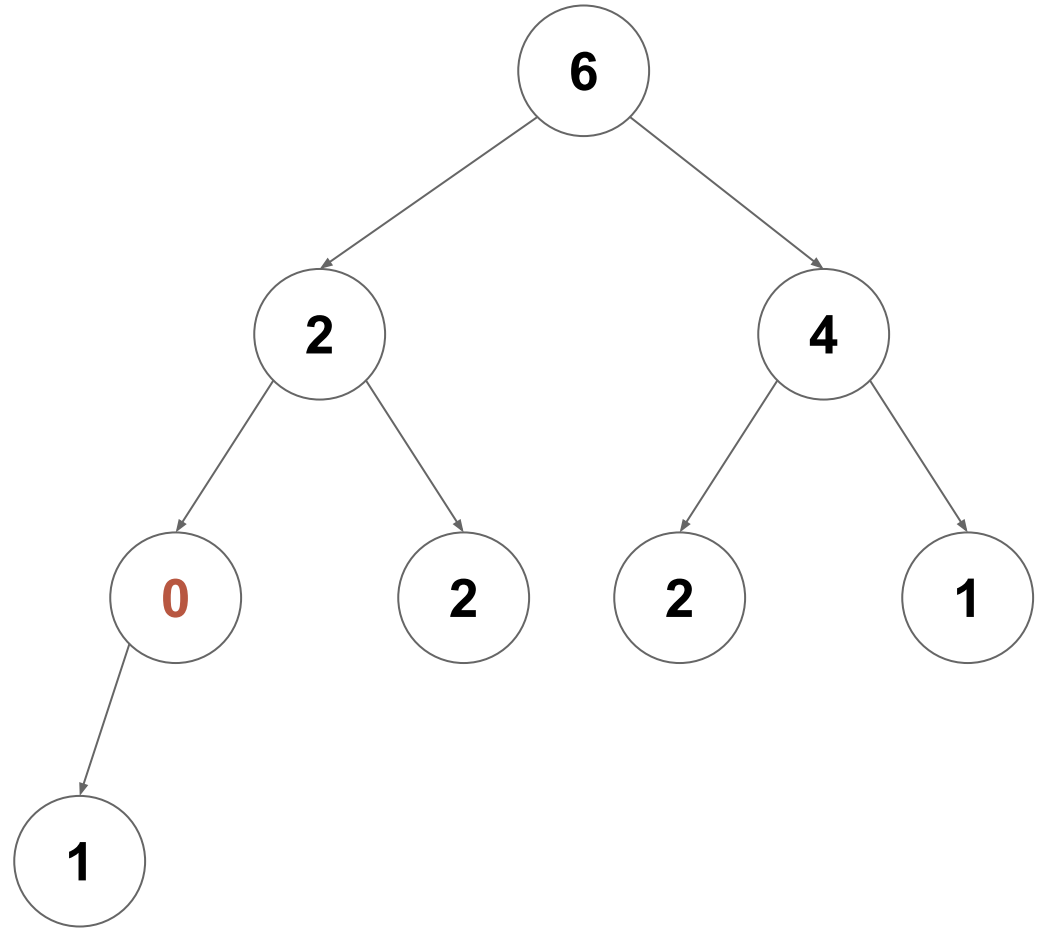
Heap . update

We now have to **fixUp** or **fixDown** based on the new value



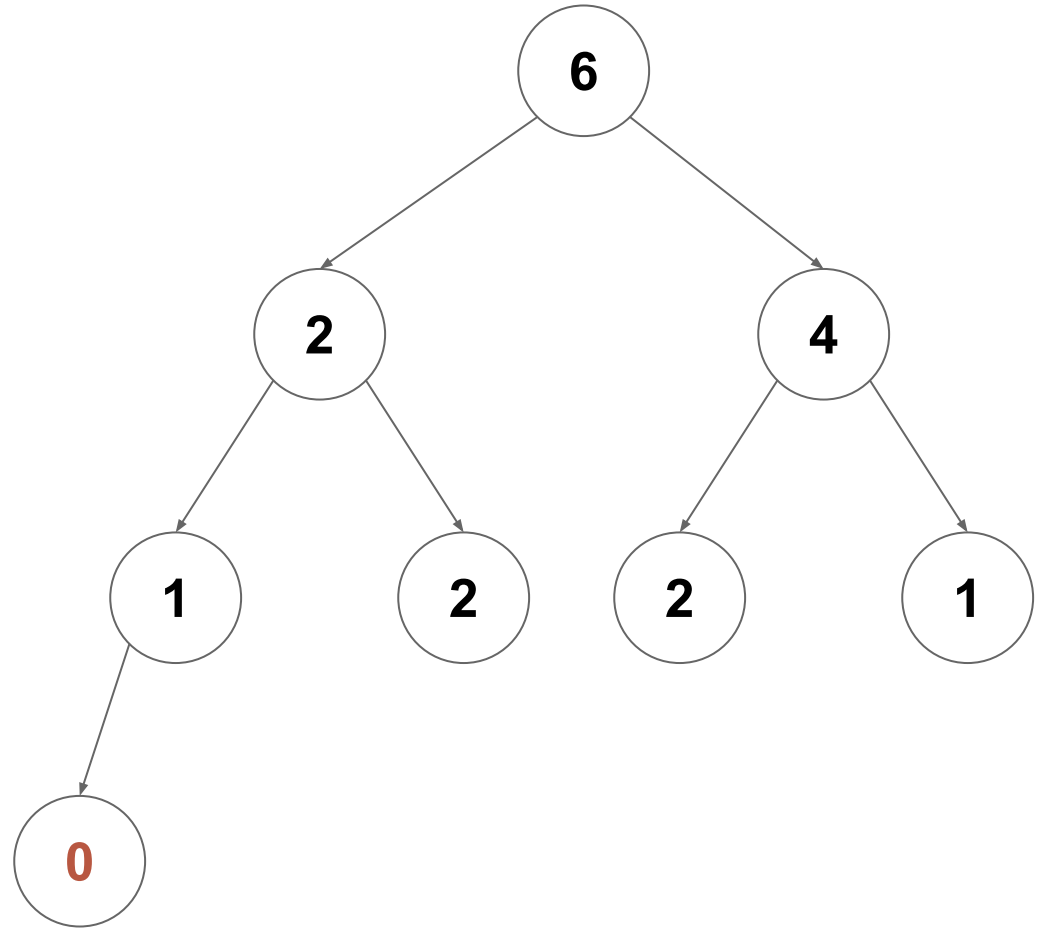
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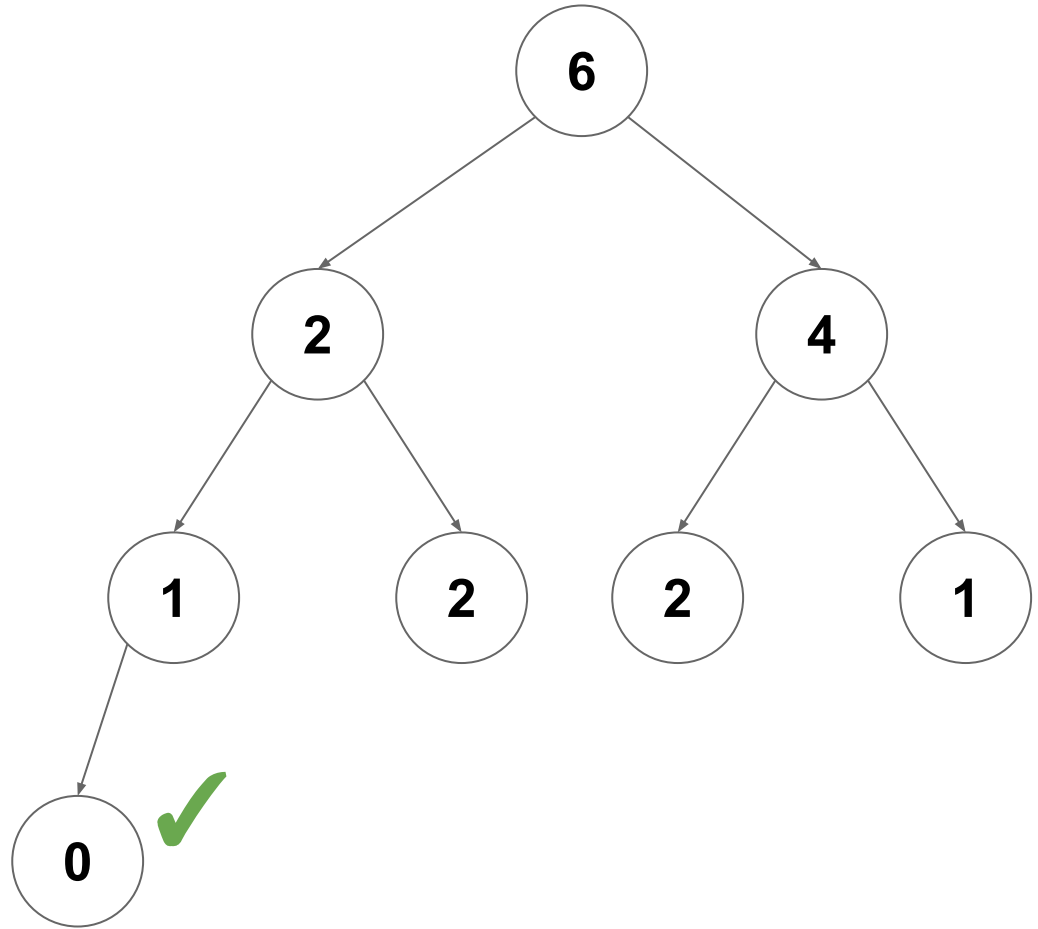
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Updating Heap Elements

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Can we apply this idea to an entire array?

Heapify

Input: Array

Output: Array re-ordered to be a heap

Heapify

Input: Array

Output: Array re-ordered to be a heap

Idea: `fixUp` or `fixDown` all n elements in the array

Heapify

Input: Array

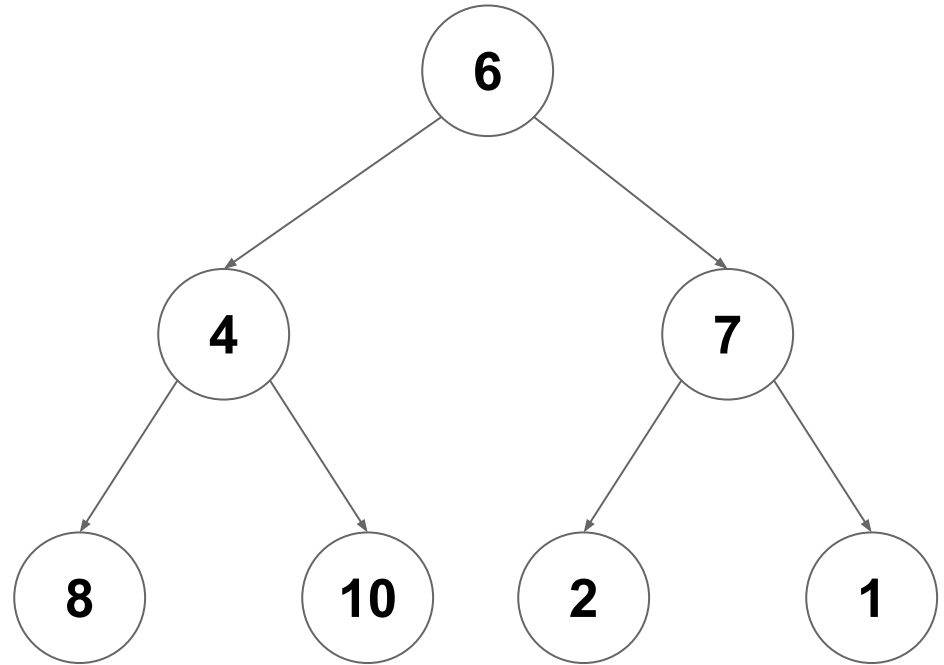
Output: Array re-ordered to be a heap

Idea: `fixUp` or `fixDown` all n elements in the array

*Given the cost of `fixUp` and `fixDown` what do we expect the complexity
Heapify will be?*

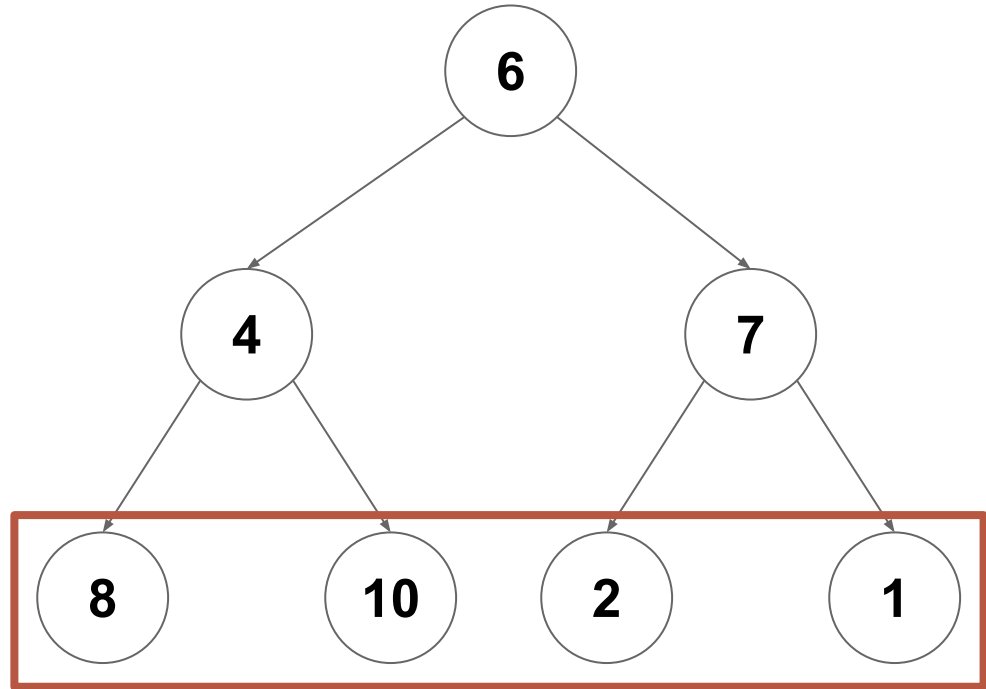
Heapify

Given an arbitrary array
(show as a tree here) turn
it into a heap



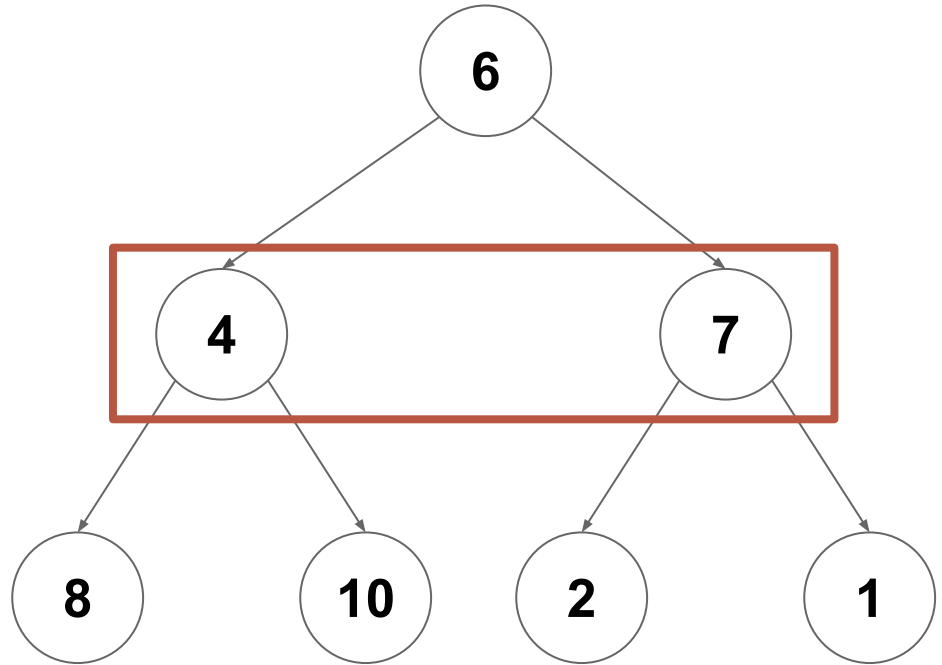
Heapify

Start at the lowest level,
and call `fixDown` on
each node (0 swaps per
node)



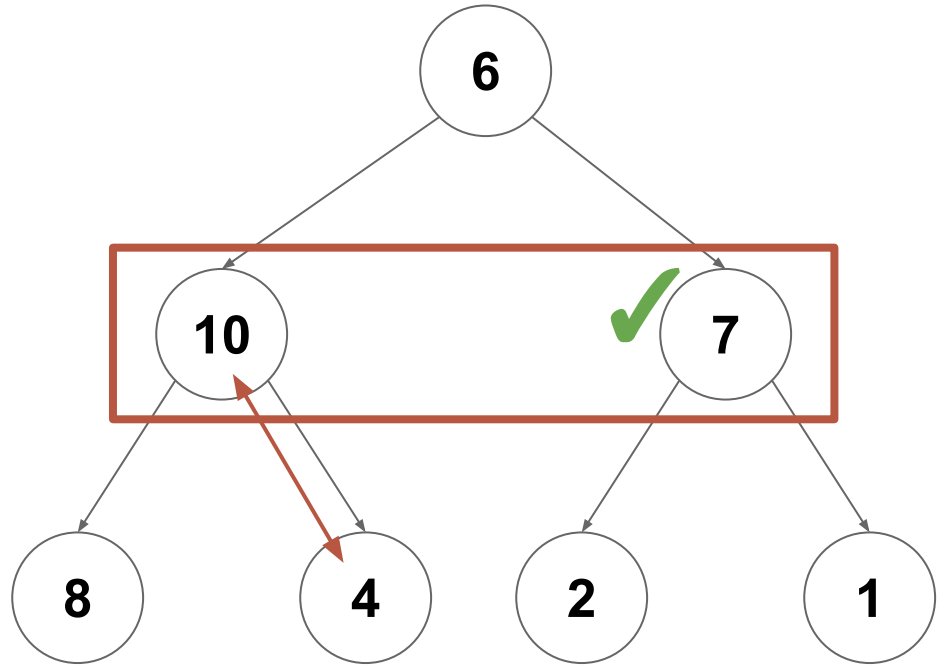
Heapify

Do the same at the next lowest level (at most one swap per node)



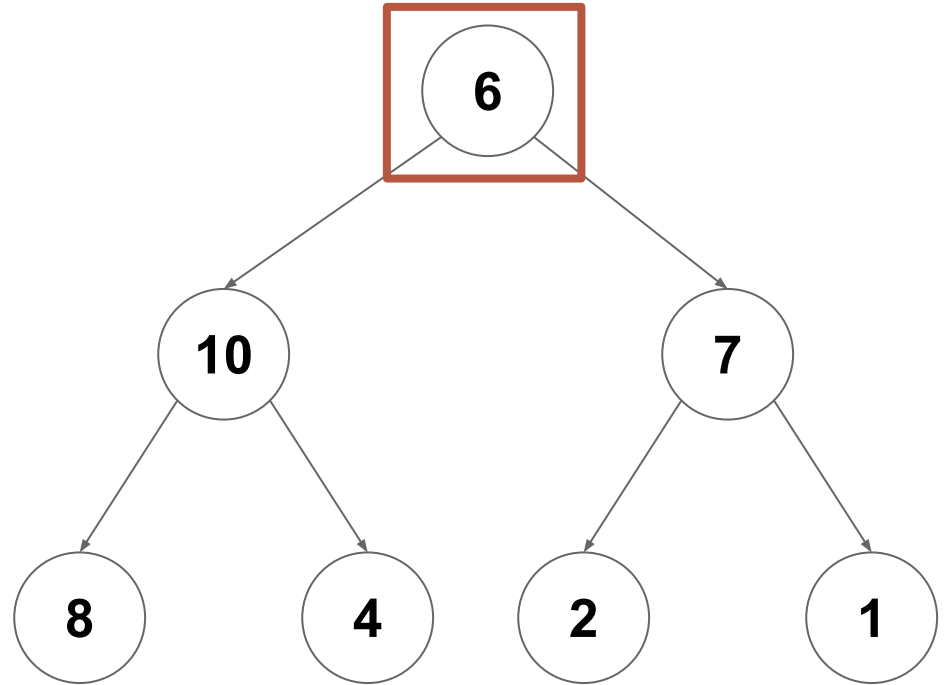
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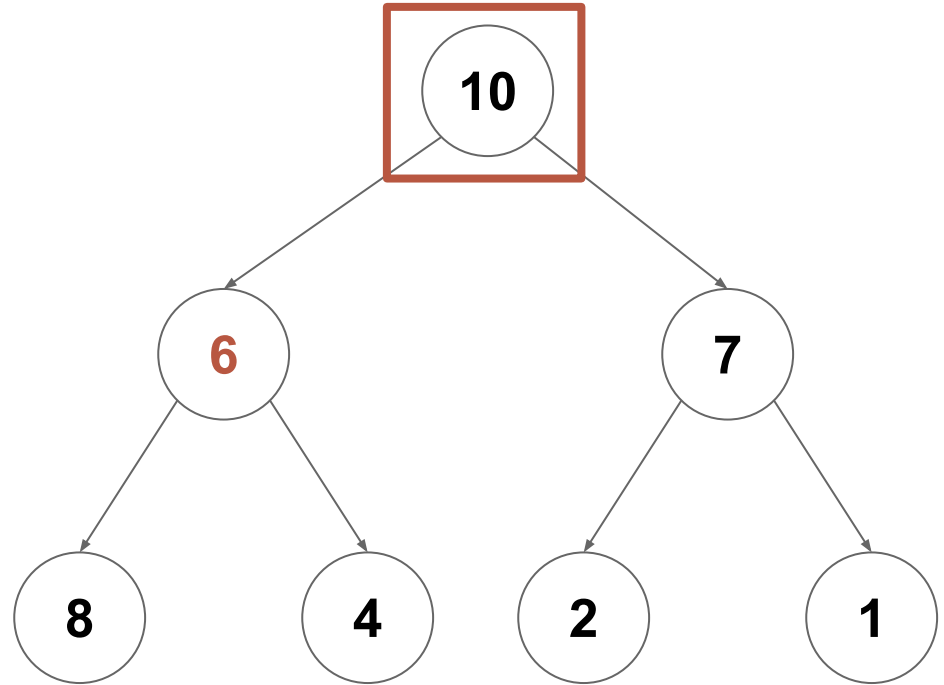
Heapify

Continue upwards (now at most 2 swaps per node)



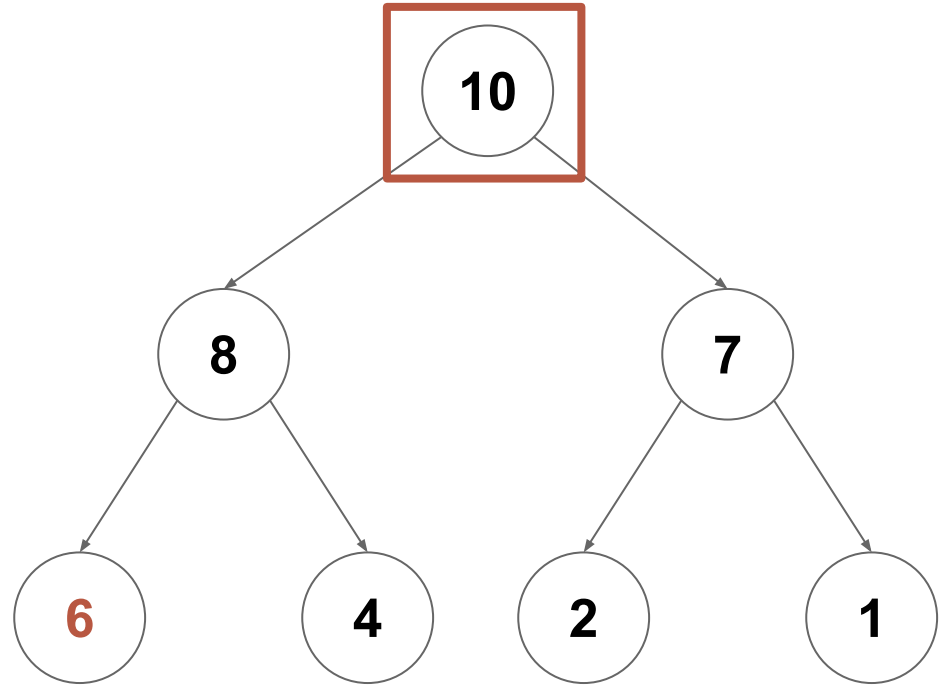
Heapify

Continue upwards (now at most 2 swaps per node)



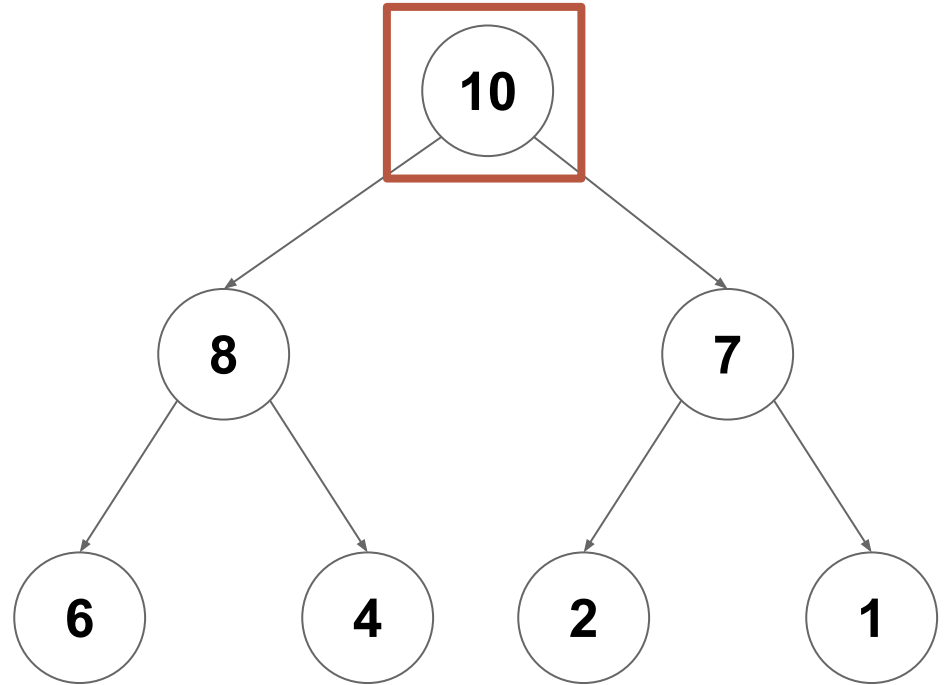
Heapify

Continue upwards (now at most 2 swaps per node)



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Heapify

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At level $\log(n)$: Call `fixDown` on all $n/2$ nodes at this level (max 0 swaps each)

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At level $\log(n)-1$: Call `fixDown` on all $n/4$ nodes at this level (max 1 swaps each)

Heapify

At level $\log(n)$: Call `fixDown` on all $n/2$ nodes at this level (max 0 swaps each)

At level $\log(n)-1$: Call `fixDown` on all $n/4$ nodes at this level (max 1 swaps each)

At level $\log(n)-2$: Call `fixDown` on all $n/8$ nodes at this level (max 2 swaps each)

Heapify

At level $\log(n)$: Call `fixDown` on all $n/2$ nodes at this level (max 0 swaps each)

At level $\log(n)-1$: Call `fixDown` on all $n/4$ nodes at this level (max 1 swaps each)

At level $\log(n)-2$: Call `fixDown` on all $n/8$ nodes at this level (max 2 swaps each)

...

At level 1: Call `fixDown` on all 1 nodes at this level (max $\log(n)$ swaps each)

Heapify

Sum the number of swaps
required by each level

$$O \left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i + 1) \right)$$

Heapify

Pull out the n as a constant and distribute multiplication

$$O \left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i + 1) \right)$$

$$O \left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i} + \frac{1}{2^i} \right)$$

Heapify

Focus on the dominant term only

$$O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$$

$$O\left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i} + \frac{1}{2^i}\right)$$

$$O\left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i}\right)$$

Heapify

Change $\log(n)$ to infinity
(can only increase
complexity class if
anything)

$$O\left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i+1)\right)$$

$$O\left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i} + \frac{1}{2^i}\right)$$

$$O\left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i}\right)$$

$$O\left(n \sum_{i=1}^{\infty} \frac{i}{2^i}\right)$$

Heapify

We can now treat the sum as a constant

$$O \left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i + 1) \right)$$

$$O \left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i} + \frac{1}{2^i} \right)$$

$$O \left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i} \right)$$

$$O \left(n \sum_{i=1}^{\infty} \frac{i}{2^i} \right)$$

This is known to converge to a constant

Heapify

Therefore we can heapify
an array of size n in $O(n)$

$$O \left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i + 1) \right)$$

$$O \left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i} + \frac{1}{2^i} \right)$$

$$O \left(n \sum_{i=1}^{\log(n)} \frac{i}{2^i} \right)$$

$$O \left(n \sum_{i=1}^{\infty} \frac{i}{2^i} \right) = O(n)$$

Heapify

Therefore we can heapify
an array of size n in $O(n)$

(but heap sort still
requires $n \log(n)$ due to
dequeue costs)

$$O \left(\sum_{i=1}^{\log(n)} \frac{n}{2^i} \cdot (i + 1) \right)$$

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Sets

A **Set** is an **unordered** collection of **unique** elements.

(order doesn't matter, and at most one copy of each item)

Sets

A **Set** is an **unordered** collection of **unique** elements.

(order doesn't matter, and at most one copy of each ~~item~~ key)

The `mutable.Set[T]` ADT

`add(element: T): Unit`

Store one copy of `element` if not already present

`apply(element: T): Boolean`

Return true if `element` is present in the set

`remove(element: T): Boolean`

Remove `element` if present, or return false if not

Bags

A **Bag** is an **unordered** collection of **non-unique** elements.

(order doesn't matter, and multiple copies with the same key is OK)

The mutable.Bag[T] ADT

`add(element: T): Unit`

Register the presence of a new (copy of) `element`

`apply(element: T): Boolean`

Return the number of copies of `element` in the bag

`remove(element: T): Boolean`

Remove one copy of `element` if present, or return false if not

Collection ADTs

Property	Seq	Set	Bag
Explicit Order	✓		
Enforced Uniqueness		✓	
Iterable	✓	✓	✓

(Rooted) Trees

(Even More) Tree Terminology

Rooted, Directed Tree - Has a single root node (node with no parents)

Parent of node X - A node with an out-edge to X (max 1 parent per node)

Child of node X - A node with an in-edge from X

Leaf - A node with no children

Depth of node X - The number of edges in the path from the root to X

Height of node X - The number of edges in the path from X to the deepest leaf

(Even More) Tree Terminology

Level of a node - Depth of the node + 1

Size of a tree (n) - The number of nodes in the tree

Height/Depth of a tree (d) - Height of the root/depth of the deepest leaf

(Even More) Tree Terminology

Binary Tree - Every vertex has at most 2 children

Complete Binary Tree - All leaves are in the deepest two levels

Full Binary Tree - All leaves are at the deepest level, therefore every vertex has exactly 0 or 2 children, and $d = \log(n)$

Quick Scala Tips

```
class TreeNode[T] (  
  var _value: T,  
  var _left: Option[TreeNode[T]]  
  var _right: Option[TreeNode[T]]  
)  
  
class Tree[T] {  
  var root: Option[TreeNode[T]] = None // empty tree  
}
```

We've seen how we can use options for objects that may not exist...

Quick Scala Tips

```
trait Tree[+T]

case class TreeNode[T] (
  value: T,
  left: Tree[T],
  right: Tree[T]
) extends Tree[T]

case object EmptyTree extends Tree[Nothing]
```

But we can also use Traits and case classes...

Quick Scala Tips

```
trait Tree[+T]
```

```
case class TreeNode[T] (
```

```
  value: T,
```

```
  left: Tree[T],
```

```
  right: Tree[T]
```

```
) extends Tree[T]
```

TreeNode and EmptyTree are
two cases of Tree

```
case object EmptyTree extends Tree[Nothing]
```

But we can also use Traits and case classes...

Case Classes/Objects

Case Classes/Objects have two important features:

1. Inline Constructors (no `new`):

```
TreeNode (10, EmptyTree, EmptyTree)
```

2. Match destructors:

```
foo match { case TreeNode (v, l, r) => ... }
```

Case Classes/Objects

```
def printTree[T](root: ImmutableTree[T], indent: Int) = {
  root match {
    case TreeNode(v, left, right) =>
      print((" " * indent) + v)
      printTree(left, indent + 2)
      printTree(right, indent + 2)

    case EmptyTree =>
      /* Do Nothing */
  }
}
```

Case Classes/Objects

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def printTree[T](root: ImmutableTree[T], indent: Int) = {  
  root match {  
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      print((" " * indent) + v)  
      printTree(left, indent + 2)  
      printTree(right, indent + 2)  
  
    case EmptyTree =>  
      /* Do Nothing */  
  }  
}
```

If `root` is a `TreeNode` with value `v`, and subtrees `left` and `right`, print `v`, then call `printTree` on `left` and `right`

Case Classes/Objects

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def printTree[T](root: ImmutableTree[T], indent: Int) = {  
  root match {  
    case TreeNode(v, left, right) =>  
      print((" " * indent) + v)  
      printTree(left, indent + 2)  
      printTree(right, indent + 2)  
    case EmptyTree =>  
      /* Do Nothing */  
  }  
}
```

If root is an `EmptyTree` then don't do anything

Computing Tree Height

The height of a tree is the height of the root

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The children of the root are each roots of the left and right subtrees

So we can compute height recursively:

$$h(\text{root}) = \begin{cases} 0 & \text{if the tree is empty} \\ 1 + \max(h(\text{root.left}), h(\text{root.right})) & \text{otherwise} \end{cases}$$

Computing Tree Height

```
def height[T](root: Tree[T]): Int = {  
  root match {  
    case EmptyTree =>  
      0  
  
    case TreeNode(v, left, right) =>  
      1 + Math.max( height(left), height(right) )  
  }  
}
```

$$h(\text{root}) = \begin{cases} 0 & \text{if the tree is empty} \\ 1 + \max(h(\text{root.left}), h(\text{root.right})) & \text{otherwise} \end{cases}$$

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  }  
}
```

Case classes have a nice mapping
onto functions with multiple cases

$$h(\text{root}) = \begin{cases} 0 & \text{if the tree is empty} \\ 1 + \max(h(\text{root.left}), h(\text{root.right})) & \text{otherwise} \end{cases}$$

Binary Search Tree

A **Binary Search Tree** is a **Binary Tree** in which each node stores a unique key, and the keys are ordered.

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- For every node X_R in the right subtree of node X : $X_R.\text{key} > X.\text{key}$

X partitions its children

Finding an Item

Goal: Find an item with key k in a BST rooted at `root`

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3. Is k less than `root.value`'s key? (if yes, search left subtree)
4. Is k greater than `root.value`'s key? (If yes, search the right subtree)

find

```
def find[V: Ordering](root: BST[V], target: V): Option[V] =
  root match {
    case TreeNode(v, left, right) =>
      if(Ordering[V].lt( target, v ))      { return find(left, target) }
      else if(Ordering[V].lt( v, target )) { return find(right, target) }
      else                                  { return Some(v) }

    case EmptyTree =>
      return None
  }
```

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What's the complexity?

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What's the complexity? (how many times do we call find)?

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What's the complexity? (how many times do we call `find`)? $O(d)$

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2. Does `root.value` have key k ? (already present! don't insert)
3. Is k less than `root.value`'s key? (call insert on left subtree)
4. Is k greater than `root.value`'s key? (call insert on right subtree)

insert

```
def insert[V: Ordering](root: BST[V], value: V): BST[V] =
  node match {
    case TreeNode(v, left, right) =>
      if(Ordering[V].lt( target, v ) ){
        return TreeNode(v, insert(left, target), right)
      } else if(Ordering[V].lt( v, target ) ){
        return TreeNode(v, left, insert(right, target))
      } else {
        return node // already present
      }

    case EmptyTree =>
      return TreeNode(value, EmptyTree, EmptyTree)
  }
```


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What is the complexity?
(how many calls to insert)?

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      } else {
        return node // already present
      }

    case EmptyTree =>
      return TreeNode(value, EmptyTree, EmptyTree)
  }
```

What is the complexity?
(how many calls to insert)? $O(d)$

Remove

Goal: Remove the item with key k from a BST rooted at **root**

1. **find** the item
2. Replace the found node with the right subtree
3. Insert the left subtree under the right

We'll look at this in more detail later, but for now...

What's the complexity? $O(d)$

Sets and Bags

So we could use this specification of a BST to implement a Set

What about bags? How could we change our BST to implement a Bag?

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So we could use this specification of a BST to implement a Set

What about bags? How could we change our BST to implement a Bag?

Idea 1: Allow multiple copies ($X_L \leq X$ instead of \prec)

Idea 2: Only store one copy of each element, but also store a count

BST Operations

Operation	Runtime
<code>find</code>	$O(d)$
<code>insert</code>	$O(d)$
<code>remove</code>	$O(d)$

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BST Operations

Operation	Runtime
<code>find</code>	$O(d)$
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<code>remove</code>	$O(d)$

What is the runtime in terms of n ? $O(n)$

Does it need to be that bad?

Next time...

Balancing Trees...